

Bcps
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Contents

| | | |
|----------|---|----------|
| 1 | Class Index | 1 |
| 1.1 | Class Hierarchy | 1 |
| 2 | Class Index | 3 |
| 2.1 | Class List | 3 |
| 3 | Class Documentation | 3 |
| 3.1 | BcpsBranchObject Class Reference | 4 |
| 3.1.1 | Detailed Description | 6 |
| 3.1.2 | Constructor & Destructor Documentation | 6 |
| 3.1.3 | Member Function Documentation | 6 |
| 3.1.4 | Member Data Documentation | 9 |
| 3.2 | BcpsBranchStrategy Class Reference | 10 |
| 3.2.1 | Detailed Description | 11 |
| 3.2.2 | Constructor & Destructor Documentation | 11 |
| 3.2.3 | Member Function Documentation | 12 |
| 3.2.4 | Member Data Documentation | 12 |
| 3.3 | BcpsConstraint Class Reference | 14 |
| 3.3.1 | Detailed Description | 14 |
| 3.3.2 | Constructor & Destructor Documentation | 14 |
| 3.4 | BcpsConstraintPool Class Reference | 15 |
| 3.4.1 | Detailed Description | 15 |
| 3.4.2 | Member Function Documentation | 15 |
| 3.5 | BcpsFieldListMod< T > Struct Template Reference | 16 |
| 3.5.1 | Detailed Description | 16 |
| 3.5.2 | Member Data Documentation | 16 |
| 3.6 | BcpsMessage Class Reference | 16 |
| 3.6.1 | Detailed Description | 17 |
| 3.7 | BcpsModel Class Reference | 17 |
| 3.7.1 | Detailed Description | 18 |
| 3.7.2 | Member Function Documentation | 18 |
| 3.7.3 | Member Data Documentation | 18 |
| 3.8 | BcpsNodeDesc Class Reference | 19 |
| 3.8.1 | Detailed Description | 21 |
| 3.8.2 | Constructor & Destructor Documentation | 21 |
| 3.8.3 | Member Function Documentation | 22 |

| | | |
|--------|--|----|
| 3.8.4 | Member Data Documentation | 25 |
| 3.9 | BcpsObject Class Reference | 25 |
| 3.9.1 | Detailed Description | 27 |
| 3.9.2 | Constructor & Destructor Documentation | 27 |
| 3.9.3 | Member Function Documentation | 27 |
| 3.9.4 | Member Data Documentation | 29 |
| 3.10 | BcpsObjectListMod Struct Reference | 30 |
| 3.10.1 | Detailed Description | 30 |
| 3.10.2 | Member Data Documentation | 31 |
| 3.11 | BcpsObjectPool Class Reference | 31 |
| 3.11.1 | Detailed Description | 32 |
| 3.11.2 | Constructor & Destructor Documentation | 32 |
| 3.11.3 | Member Function Documentation | 32 |
| 3.12 | BcpsSolution Class Reference | 33 |
| 3.12.1 | Detailed Description | 34 |
| 3.12.2 | Constructor & Destructor Documentation | 34 |
| 3.12.3 | Member Function Documentation | 35 |
| 3.12.4 | Member Data Documentation | 35 |
| 3.13 | BcpsSubTree Class Reference | 36 |
| 3.13.1 | Detailed Description | 36 |
| 3.14 | BcpsTreeNode Class Reference | 36 |
| 3.14.1 | Detailed Description | 37 |
| 3.14.2 | Constructor & Destructor Documentation | 37 |
| 3.14.3 | Member Function Documentation | 37 |
| 3.14.4 | Member Data Documentation | 39 |
| 3.15 | BcpsVariable Class Reference | 39 |
| 3.15.1 | Detailed Description | 40 |
| 3.15.2 | Constructor & Destructor Documentation | 40 |
| 3.16 | BcpsVariablePool Class Reference | 40 |
| 3.16.1 | Detailed Description | 41 |
| 3.16.2 | Member Function Documentation | 41 |

1 Class Index

1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

```

std::basic_fstream< char >
std::basic_fstream< wchar_t >
std::basic_ifstream< char >
std::basic_ifstream< wchar_t >
std::basic_ios< char >
std::basic_ios< wchar_t >
std::basic_iostream< char >
std::basic_iostream< wchar_t >
std::basic_istream< char >
std::basic_istream< wchar_t >
std::basic_istreamstream< char >
std::basic_istreamstream< wchar_t >
std::basic_ofstream< char >
std::basic_ofstream< wchar_t >
std::basic_ostream< char >
std::basic_ostream< wchar_t >
std::basic_ostreamstream< char >
std::basic_ostreamstream< wchar_t >
std::basic_string< char >
std::basic_string< wchar_t >
std::basic_stringstream< char >
std::basic_stringstream< wchar_t >

```

| | |
|------------------------------------|--------------------|
| BcpsBranchObject | 4 |
| BcpsBranchStrategy | 10 |
| BcpsFieldListMod< T > | 16 |
| BcpsMessage | 16 |
| BcpsModel | 17 |
| BcpsNodeDesc | 19 |
| BcpsObject | 25 |
| BcpsConstraint | 14 |
| BcpsVariable | 39 |
| BcpsObjectListMod | 30 |
| BcpsObjectPool | 31 |
| BcpsConstraintPool | 15 |
| BcpsVariablePool | 40 |
| BcpsSolution | 33 |
| BcpsSubTree | 36 |
| BcpsTreeNode | 36 |

2 Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

| | |
|--|----|
| BcpsBranchObject | |
| BcpsBranchObject contains the member data required when choosing branching entities and executing actual branching | 4 |
| BcpsBranchStrategy | |
| Branching strategy specifies: (1) how to select a candidate set of branching objects (2) how to compare two branching objects | 10 |
| BcpsConstraint | 14 |
| BcpsConstraintPool | 15 |
| BcpsFieldListMod< T > | |
| This class contains modifications for a single <code>std::vector<T></code> object | 16 |
| BcpsMessage | 16 |
| BcpsModel | 17 |
| BcpsNodeDesc | |
| For a given type, the <code>objectVecStorage_</code> structure holds the description | 19 |
| BcpsObject | |
| A class for describing the objects that comprise a BCPS subproblem | 25 |
| BcpsObjectListMod | |
| Here is the set of <code>vectorMod_</code> objects that represent the list of objects of a particular type (either in relative or explicit form) | 30 |
| BcpsObjectPool | |
| Object pool is used to store objects | 31 |
| BcpsSolution | |
| This class holds the solution objects | 33 |
| BcpsSubTree | |
| This class is the data structure for storing a subtree within BCPS | 36 |
| BcpsTreeNode | |
| This class contain the data for a BCPS search tree node | 36 |
| BcpsVariable | 39 |
| BcpsVariablePool | 40 |

3 Class Documentation

3.1 BcpsBranchObject Class Reference

[BcpsBranchObject](#) contains the member data required when choosing branching entities and excuting actual branching.

```
#include <BcpsBranchObject.h>
```

Public Member Functions

- [BcpsBranchObject](#) ()
Default Constructor.
- [BcpsBranchObject](#) ([BcpsModel](#) **model*)
Useful constructor.
- [BcpsBranchObject](#) ([BcpsModel](#) **model*, int *objectIndex*, int *direction*, double *value*)
Useful constructor.
- [BcpsBranchObject](#) ([BcpsModel](#) **model*, int *objectIndex*, int *upScore*, double *downScore*, int *direction*, double *value*)
Useful constructor.
- [BcpsBranchObject](#) (const [BcpsBranchObject](#) &)
Copy constructor.
- virtual ~[BcpsBranchObject](#) ()
Destructor.
- [BcpsBranchObject](#) & *operator=* (const [BcpsBranchObject](#) &*rhs*)
Assignment operator.
- virtual [BcpsBranchObject](#) * *clone* () const =0
Clone a object.
- int *getType* ()
Get type.
- void *setType* (int *t*)
Set type.
- virtual int *numBranches* () const
The number of branch arms created for this branch object.
- virtual int *numBranchesLeft* () const
The number of branch arms left to be evaluated.
- virtual double *branch* (bool *normalBranch*=false)=0
Perform branching as specified by the branching object.
- virtual void *print* (bool *normalBranch*)
Print information about this branching object.
- virtual bool *boundBranch* () const
Return true if branching should fix object bounds.
- int *getObjectIndex* () const
Object objectIndex.
- void *setObjectIndex* (int *ind*)
Set object objectIndex.
- double *getUpScore* () const
Get integer score.
- void *setUpScore* (double *score*)
Set integer score.
- double *getDownScore* () const

- Get double score.*
- void [setDownScore](#) (double score)
 - Get double score.*
- int [getDirection](#) () const
 - Returns a code indicating the active arm of the branching object.*
- void [setDirection](#) (int direction)
 - Set the direction of the branching object.*
- double [getValue](#) () const
 - Return object branching value.*
- [BcpsModel](#) * [model](#) () const
 - Return model.*
- virtual AlpsReturnStatus [encode](#) (AlpsEncoded *encoded) const
 - Pack to an encoded object.*
- virtual AlpsReturnStatus [decode](#) (AlpsEncoded &encoded)
 - Unpack a branching object from an encoded object.*

Protected Member Functions

- AlpsReturnStatus [encodeBcps](#) (AlpsEncoded *encoded) const
 - Pack Bcps portion to an encoded object.*
- AlpsReturnStatus [decodeBcps](#) (AlpsEncoded &encoded)
 - Unpack Bcps portion from an encoded object.*

Protected Attributes

- int [type_](#)
 - Type of branching.*
- [BcpsModel](#) * [model_](#)
 - The model that owns this branch object.*
- int [objectIndex_](#)
 - Branch object index.*
- double [upScore_](#)
 - Quality/Goodness of this object.*
- double [downScore_](#)
 - The score of branching down.*
- int [direction_](#)
 - Information required to do branching.*
- double [value_](#)
 - Current branching value.*
- int [numBranchesLeft_](#)
 - Number of arms remaining to be evaluated.*

3.1.1 Detailed Description

[BcpsBranchObject](#) contains the member data required when choosing branching entities and excuting actual branching. It also has the member funtions to do branching by adjusting bounds, etc. in solver. Branching objects can be simple integer variables or more complicated objects like SOS.

Definition at line 47 of file BcpsBranchObject.h.

3.1.2 Constructor & Destructor Documentation

3.1.2.1 BcpsBranchObject::BcpsBranchObject () [inline]

Default Constructor.

Definition at line 91 of file BcpsBranchObject.h.

3.1.2.2 BcpsBranchObject::BcpsBranchObject (BcpsModel * model) [inline]

Useful constructor.

Definition at line 104 of file BcpsBranchObject.h.

3.1.2.3 BcpsBranchObject::BcpsBranchObject (BcpsModel * model, int objectIndex, int direction, double value) [inline]

Useful constructor.

Definition at line 117 of file BcpsBranchObject.h.

3.1.2.4 BcpsBranchObject::BcpsBranchObject (BcpsModel * model, int objectIndex, int upScore, double downScore, int direction, double value) [inline]

Useful constructor.

Definition at line 133 of file BcpsBranchObject.h.

3.1.2.5 BcpsBranchObject::BcpsBranchObject (const BcpsBranchObject &)

Copy constructor.

3.1.2.6 virtual BcpsBranchObject::~BcpsBranchObject () [inline],[virtual]

Destructor.

Definition at line 154 of file BcpsBranchObject.h.

3.1.3 Member Function Documentation

3.1.3.1 BcpsBranchObject& BcpsBranchObject::operator= (const BcpsBranchObject & rhs)

Assignment operator.

3.1.3.2 virtual BcpsBranchObject* BcpsBranchObject::clone () const [pure virtual]

Clone a object.

3.1.3.3 `int BcpsBranchObject::getType () [inline]`

Get type.

Definition at line 163 of file BcpsBranchObject.h.

3.1.3.4 `void BcpsBranchObject::setType (int t) [inline]`

Set type.

Definition at line 166 of file BcpsBranchObject.h.

3.1.3.5 `virtual int BcpsBranchObject::numBranches () const [inline],[virtual]`

The number of branch arms created for this branch object.

Definition at line 169 of file BcpsBranchObject.h.

3.1.3.6 `virtual int BcpsBranchObject::numBranchesLeft () const [inline],[virtual]`

The number of branch arms left to be evaluated.

Definition at line 172 of file BcpsBranchObject.h.

3.1.3.7 `virtual double BcpsBranchObject::branch (bool normalBranch = false) [pure virtual]`

Perform branching as specified by the branching object.

Also, update the status of this branching object.

3.1.3.8 `virtual void BcpsBranchObject::print (bool normalBranch) [inline],[virtual]`

Print information about this branching object.

Definition at line 180 of file BcpsBranchObject.h.

3.1.3.9 `virtual bool BcpsBranchObject::boundBranch () const [inline],[virtual]`

Return true if branching should fix object bounds.

Definition at line 183 of file BcpsBranchObject.h.

3.1.3.10 `int BcpsBranchObject::getObjectIndex () const [inline]`

Object objectIndex.

Definition at line 186 of file BcpsBranchObject.h.

3.1.3.11 `void BcpsBranchObject::setObjectIndex (int ind) [inline]`

Set object objectIndex.

Definition at line 189 of file BcpsBranchObject.h.

3.1.3.12 `double BcpsBranchObject::getUpScore () const [inline]`

Get integer score.

Definition at line 192 of file BcpsBranchObject.h.

3.1.3.13 `void BcpsBranchObject::setUpScore (double score) [inline]`

Set integer score.

Definition at line 195 of file BcpsBranchObject.h.

3.1.3.14 `double BcpsBranchObject::getDownScore () const [inline]`

Get double score.

Definition at line 198 of file BcpsBranchObject.h.

3.1.3.15 `void BcpsBranchObject::setDownScore (double score) [inline]`

Get double score.

Definition at line 201 of file BcpsBranchObject.h.

3.1.3.16 `int BcpsBranchObject::getDirection () const [inline]`

Returns a code indicating the active arm of the branching object.

Definition at line 204 of file BcpsBranchObject.h.

3.1.3.17 `void BcpsBranchObject::setDirection (int direction) [inline]`

Set the direction of the branching object.

Definition at line 207 of file BcpsBranchObject.h.

3.1.3.18 `double BcpsBranchObject::getValue () const [inline]`

Return object branching value.

Definition at line 210 of file BcpsBranchObject.h.

3.1.3.19 `BcpsModel* BcpsBranchObject::model () const [inline]`

Return model.

Definition at line 213 of file BcpsBranchObject.h.

3.1.3.20 `AlpsReturnStatus BcpsBranchObject::encodeBcps (AlpsEncoded * encoded) const [inline],[protected]`

Pack Bcps portion to an encoded object.

Definition at line 218 of file BcpsBranchObject.h.

3.1.3.21 `AlpsReturnStatus BcpsBranchObject::decodeBcps (AlpsEncoded & encoded) [inline],[protected]`

Unpack Bcps portion from an encoded object.

Definition at line 232 of file BcpsBranchObject.h.

3.1.3.22 `virtual AlpsReturnStatus BcpsBranchObject::encode (AlpsEncoded * encoded) const [inline],[virtual]`

Pack to an encoded object.

Definition at line 248 of file BcpsBranchObject.h.

3.1.3.23 `virtual AlpsResponseStatus BcpsBranchObject::decode (AlpsEncoded & encoded)` `[inline], [virtual]`

Unpack a branching object from an encoded object.

Definition at line 256 of file BcpsBranchObject.h.

3.1.4 Member Data Documentation

3.1.4.1 `int BcpsBranchObject::type_` `[protected]`

Type of branching.

Definition at line 52 of file BcpsBranchObject.h.

3.1.4.2 `BcpsModel* BcpsBranchObject::model_` `[protected]`

The model that owns this branch object.

Definition at line 55 of file BcpsBranchObject.h.

3.1.4.3 `int BcpsBranchObject::objectIndex_` `[protected]`

Branch object index.

The index is not the same as variable index. For integer branching, the index refers to the position in the integer object array/vector.

Definition at line 60 of file BcpsBranchObject.h.

3.1.4.4 `double BcpsBranchObject::upScore_` `[protected]`

Quality/Goodness of this object.

They are set when creating candidate branching entities, and used when comparing two branching entities. Derived class can add more metrics. The score of branching up. Used for binary branching only.

Definition at line 69 of file BcpsBranchObject.h.

3.1.4.5 `double BcpsBranchObject::downScore_` `[protected]`

The score of branching down.

Used for binary branching only.

Definition at line 72 of file BcpsBranchObject.h.

3.1.4.6 `int BcpsBranchObject::direction_` `[protected]`

Information required to do branching.

Used for binary branching only. The direction of the active branch. Down is -1, up is 1.

Definition at line 78 of file BcpsBranchObject.h.

3.1.4.7 `double BcpsBranchObject::value_` `[protected]`

Current branching value.

For integer, it can be fractional solution value.

Definition at line 82 of file BcpsBranchObject.h.

3.1.4.8 int BcpsBranchObject::numBranchesLeft_ [protected]

Number of arms remaining to be evaluated.

Definition at line 85 of file BcpsBranchObject.h.

The documentation for this class was generated from the following file:

- BcpsBranchObject.h

3.2 BcpsBranchStrategy Class Reference

Branching strategy specifies: (1) how to select a candidate set of branching objects (2) how to compare two branching objects.

```
#include <BcpsBranchStrategy.h>
```

Public Member Functions

- [BcpsBranchStrategy](#) ()
Default Constructor.
- [BcpsBranchStrategy](#) (BcpsModel *m)
Useful Constructor.
- virtual [~BcpsBranchStrategy](#) ()
Destructor.
- virtual [BcpsBranchStrategy](#) * [clone](#) () const =0
Clone a branch strategy.
- int [getType](#) ()
Get type.
- void [setType](#) (int t)
Set type.
- void [setModel](#) (BcpsModel *m)
Set model.
- virtual void [clearBest](#) (BcpsModel *model)
Clear branching strategy environment before starting a new round of selecting the best branch object.
- virtual int [createCandBranchObjects](#) (int numPassesLeft, double ub)
Create a set of candidate branching objects.
- virtual int [betterBranchObject](#) (BcpsBranchObject *b, BcpsBranchObject *bestSoFar)=0
Compare branching object thisOne to bestSoFar.
- virtual BcpsBranchObject * [bestBranchObject](#) ()
Compare branching objects in branchObjects_.
- int [getNumBranchObjects](#) ()
Set/get branching objects.

Protected Attributes

- int `type_`
Type of branching strategy.
- `BcpsModel *` `model_`
Pointer to model.
- int `numBranchObjects_`
Following members are used to store candidate branching objects.
- `BcpsBranchObject **` `branchObjects_`
The set of candidate branching objects.
- `BcpsBranchObject *` `bestBranchObject_`
Following members are used to store information about best branching object found so far.
- double `bestChangeUp_`
Change up for best.
- int `bestNumberUp_`
Number of infeasibilities for up.
- double `bestChangeDown_`
Change down for best.
- int `bestNumberDown_`
Number of infeasibilities for down.

3.2.1 Detailed Description

Branching strategy specifies: (1) how to select a candidate set of branching objects (2) how to compare two branching objects.

Definition at line 39 of file `BcpsBranchStrategy.h`.

3.2.2 Constructor & Destructor Documentation

3.2.2.1 `BcpsBranchStrategy::BcpsBranchStrategy ()` `[inline]`

Default Constructor.

Definition at line 83 of file `BcpsBranchStrategy.h`.

3.2.2.2 `BcpsBranchStrategy::BcpsBranchStrategy (BcpsModel * m)` `[inline]`

Useful Constructor.

Definition at line 95 of file `BcpsBranchStrategy.h`.

3.2.2.3 `virtual BcpsBranchStrategy::~BcpsBranchStrategy ()` `[inline], [virtual]`

Destructor.

Definition at line 107 of file `BcpsBranchStrategy.h`.

3.2.3 Member Function Documentation

3.2.3.1 `virtual BcpsBranchStrategy* BcpsBranchStrategy::clone () const` `[pure virtual]`

Clone a branch strategy.

3.2.3.2 `int BcpsBranchStrategy::getType ()` `[inline]`

Get type.

Definition at line 118 of file BcpsBranchStrategy.h.

3.2.3.3 `void BcpsBranchStrategy::setType (int t)` `[inline]`

Set type.

Definition at line 121 of file BcpsBranchStrategy.h.

3.2.3.4 `void BcpsBranchStrategy::setModel (BcpsModel * m)` `[inline]`

Set model.

Definition at line 124 of file BcpsBranchStrategy.h.

3.2.3.5 `int BcpsBranchStrategy::getNumBranchObjects ()` `[inline]`

Set/get branching objects.

Definition at line 128 of file BcpsBranchStrategy.h.

3.2.3.6 `virtual void BcpsBranchStrategy::clearBest (BcpsModel * model)` `[inline],[virtual]`

Clear branching strategy environment before starting a new round of selecting the best branch object.

Definition at line 138 of file BcpsBranchStrategy.h.

3.2.3.7 `virtual int BcpsBranchStrategy::createCandBranchObjects (int numPassesLeft, double ub)` `[inline],[virtual]`

Create a set of candidate branching objects.

Definition at line 147 of file BcpsBranchStrategy.h.

3.2.3.8 `virtual int BcpsBranchStrategy::betterBranchObject (BcpsBranchObject * b, BcpsBranchObject * bestSoFar)`
`[pure virtual]`

Compare branching object thisOne to bestSoFar.

If thisOne is better than bestObject, return branching direction(1 or -1), otherwise return 0. If bestSoFar is NULL, then always return branching direction(1 or -1).

3.2.3.9 `virtual BcpsBranchObject* BcpsBranchStrategy::bestBranchObject ()` `[virtual]`

Compare branching objects in branchObjects_.

Return the index of the best branching object. Also, set branch direction in the best object.

3.2.4 Member Data Documentation

3.2.4.1 `int BcpsBranchStrategy::type_` `[protected]`

Type of branching strategy.

Definition at line 48 of file BcpsBranchStrategy.h.

3.2.4.2 `BcpsModel* BcpsBranchStrategy::model_` `[protected]`

Pointer to model.

Definition at line 51 of file BcpsBranchStrategy.h.

3.2.4.3 `int BcpsBranchStrategy::numBranchObjects_` `[protected]`

Following members are used to store candidate branching objects.

NOTE: They are required to be cleared before starting another round of selecting. Number of candidate branching objects.

Definition at line 58 of file BcpsBranchStrategy.h.

3.2.4.4 `BcpsBranchObject** BcpsBranchStrategy::branchObjects_` `[protected]`

The set of candiate branching objects.

Definition at line 60 of file BcpsBranchStrategy.h.

3.2.4.5 `BcpsBranchObject* BcpsBranchStrategy::bestBranchObject_` `[protected]`

Following members are used to store information about best branching object found so far.

NOTE: They are required to be cleared before starting another round of selecting. Best branching object found so far.

Definition at line 69 of file BcpsBranchStrategy.h.

3.2.4.6 `double BcpsBranchStrategy::bestChangeUp_` `[protected]`

Change up for best.

Definition at line 71 of file BcpsBranchStrategy.h.

3.2.4.7 `int BcpsBranchStrategy::bestNumberUp_` `[protected]`

Number of infeasibilities for up.

Definition at line 73 of file BcpsBranchStrategy.h.

3.2.4.8 `double BcpsBranchStrategy::bestChangeDown_` `[protected]`

Change down for best.

Definition at line 75 of file BcpsBranchStrategy.h.

3.2.4.9 `int BcpsBranchStrategy::bestNumberDown_` `[protected]`

Number of infeasibilities for down.

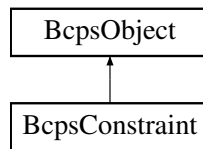
Definition at line 77 of file BcpsBranchStrategy.h.

The documentation for this class was generated from the following file:

- BcpsBranchStrategy.h

3.3 BcpsConstraint Class Reference

Inheritance diagram for BcpsConstraint:



Public Member Functions

- [BcpsConstraint](#) ()
Default constructor.
- [BcpsConstraint](#) (double lbh, double ubh, double lbs, double ubs)
Useful constructor.
- virtual [~BcpsConstraint](#) ()
Destructor constructor.
- [BcpsConstraint](#) (const [BcpsConstraint](#) &rhs)
Copy constructor.

Additional Inherited Members

3.3.1 Detailed Description

Definition at line 355 of file BcpsObject.h.

3.3.2 Constructor & Destructor Documentation

3.3.2.1 `BcpsConstraint::BcpsConstraint () [inline]`

Default constructor.

Definition at line 359 of file BcpsObject.h.

3.3.2.2 `BcpsConstraint::BcpsConstraint (double lbh, double ubh, double lbs, double ubs) [inline]`

Useful constructor.

Definition at line 362 of file BcpsObject.h.

3.3.2.3 `virtual BcpsConstraint::~~BcpsConstraint () [inline],[virtual]`

Destructor constructor.

Definition at line 368 of file BcpsObject.h.

3.3.2.4 `BcpsConstraint::BcpsConstraint (const BcpsConstraint & rhs) [inline]`

Copy constructor.

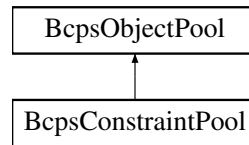
Definition at line 371 of file BcpsObject.h.

The documentation for this class was generated from the following file:

- BcpsObject.h

3.4 BcpsConstraintPool Class Reference

Inheritance diagram for BcpsConstraintPool:



Public Member Functions

- void [addConstraint](#) ([BcpsConstraint](#) *con)
Add a constraint to pool.
- void [deleteConstraint](#) (int k)
Delete constraint k from pool.
- int [getNumConstraints](#) () const
Query how many constraints are in the pool.
- const std::vector
< [AlpsKnowledge](#) * > & [getConstraints](#) () const
Get the vector of constraints.
- [AlpsKnowledge](#) * [getConstraint](#) (int k) const
Get a constraints.

3.4.1 Detailed Description

Definition at line 104 of file BcpsObjectPool.h.

3.4.2 Member Function Documentation

3.4.2.1 int BcpsConstraintPool::getNumConstraints () const [inline]

Query how many constraints are in the pool.

Definition at line 116 of file BcpsObjectPool.h.

3.4.2.2 const std::vector<AlpsKnowledge*>& BcpsConstraintPool::getConstraints () const [inline]

Get the vector of constraints.

Definition at line 119 of file BcpsObjectPool.h.

3.4.2.3 AlpsKnowledge* BcpsConstraintPool::getConstraint (int k) const [inline]

Get a constraints.

Definition at line 122 of file BcpsObjectPool.h.

The documentation for this class was generated from the following file:

- BcpsObjectPool.h

3.5 BcpsFieldListMod< T > Struct Template Reference

This class contains modifications for a single `std::vector<T>` object.

```
#include <BcpsNodeDesc.h>
```

Public Attributes

- bool `relative`
How the modification is stored, explicit means complete replacement, relative means relative to some other explicit object vector ("explicit" is a key word so we can't name the field that.)
- int `numModify`
The number of entries to be modified.
- int * `posModify`
The positions to be modified.
- T * `entries`
Values.

3.5.1 Detailed Description

```
template<class T>struct BcpsFieldListMod< T >
```

This class contains modifications for a single `std::vector<T>` object.

Definition at line 39 of file BcpsNodeDesc.h.

3.5.2 Member Data Documentation

3.5.2.1 template<class T> int BcpsFieldListMod< T >::numModify

The number of entries to be modified.

Definition at line 47 of file BcpsNodeDesc.h.

3.5.2.2 template<class T> int* BcpsFieldListMod< T >::posModify

The positions to be modified.

Definition at line 50 of file BcpsNodeDesc.h.

The documentation for this struct was generated from the following file:

- BcpsNodeDesc.h

3.6 BcpsMessage Class Reference

Public Member Functions

Constructors etc

- [BcpsMessage](#) (Language language=us_en)
Constructor.

3.6.1 Detailed Description

Definition at line 43 of file BcpsMessage.h.

The documentation for this class was generated from the following file:

- BcpsMessage.h

3.7 BcpsModel Class Reference

Public Member Functions

- `std::vector< BcpsVariable * > getVariables () const`
Return list of variables.
- `std::vector< BcpsConstraint * > getConstrints () const`
Return list of constraints.
- `CoinMessageHandler * bcpsMessageHandler () const`
Get the message handler.
- `CoinMessages bcpsMessages ()`
Return messages.
- `AlpsReturnStatus encodeBcps (AlpsEncoded *encoded) const`
Pack Bcps portion of model into an encoded object.
- `AlpsReturnStatus decodeBcps (AlpsEncoded &encoded)`
Unpack Bcps portion of model from an encoded object.
- `std::vector< BcpsConstraint * > & getConstraints ()`
Get variables and constraints.
- `void setConstraints (BcpsConstraint **con, int size)`
Set variables and constraints.

Protected Attributes

- `std::vector< BcpsConstraint * > constraints_`
Constraints input by users (before preprocessing).
- `std::vector< BcpsVariable * > variables_`
Variables input by users (before preprocessing).
- `int numCoreConstraints_`
Number of core constraints.
- `int numCoreVariables_`
Number of core variables.
- `CoinMessageHandler * bcpsMessageHandler_`
Message handler.
- `CoinMessages bcpsMessages_`
Bcps messages.

3.7.1 Detailed Description

Definition at line 40 of file BcpsModel.h.

3.7.2 Member Function Documentation

3.7.2.1 `std::vector<BcpsVariable*> BcpsModel::getVariables () const` `[inline]`

Return list of variables.

Definition at line 117 of file BcpsModel.h.

3.7.2.2 `std::vector<BcpsConstraint*> BcpsModel::getConstrints () const` `[inline]`

Return list of constraints.

Definition at line 120 of file BcpsModel.h.

3.7.2.3 `CoinMessageHandler* BcpsModel::bcpsMessageHandler () const` `[inline]`

Get the message handler.

Definition at line 123 of file BcpsModel.h.

3.7.2.4 `CoinMessages BcpsModel::bcpsMessages ()` `[inline]`

Return messages.

Definition at line 127 of file BcpsModel.h.

3.7.2.5 `AlpsReturnStatus BcpsModel::encodeBcps (AlpsEncoded * encoded) const`

Pack Bcps portion of model into an encoded object.

3.7.2.6 `AlpsReturnStatus BcpsModel::decodeBcps (AlpsEncoded & encoded)`

Unpack Bcps portion of model from an encoded object.

3.7.3 Member Data Documentation

3.7.3.1 `std::vector<BcpsConstraint*> BcpsModel::constraints_` `[protected]`

Constraints input by users (before preprocessing).

Definition at line 45 of file BcpsModel.h.

3.7.3.2 `std::vector<BcpsVariable*> BcpsModel::variables_` `[protected]`

Variables input by users (before preprocessing).

Definition at line 48 of file BcpsModel.h.

3.7.3.3 `int BcpsModel::numCoreConstraints_` `[protected]`

Number of core constraints.

By default, all input constraints are core.

Definition at line 54 of file BcpsModel.h.

3.7.3.4 int BcpsModel::numCoreVariables_ [protected]

Number of core variables.

By default, all input variables are core.

Definition at line 57 of file BcpsModel.h.

3.7.3.5 CoinMessageHandler* BcpsModel::bcpsMessageHandler_ [protected]

Message handler.

Definition at line 60 of file BcpsModel.h.

3.7.3.6 CoinMessages BcpsModel::bcpsMessages_ [protected]

Bcps messages.

Definition at line 63 of file BcpsModel.h.

The documentation for this class was generated from the following file:

- BcpsModel.h

3.8 BcpsNodeDesc Class Reference

For a given type, the objectVecStorage_ structure holds the description.

```
#include <BcpsNodeDesc.h>
```

Public Member Functions

- [BcpsNodeDesc](#) ()
Default constructor.
- [BcpsNodeDesc](#) (BcpsModel *m)
Useful constructor.
- virtual [~BcpsNodeDesc](#) ()
Destructor.
- void [initToNull](#) ()
Initialize member data.
- void [setVars](#) (int numRem, const int *posRem, int numAdd, const [BcpsObject](#) **objects, bool relvlh, int numvlh, const int *vlhp, const double *vlhe, bool relvuh, int numvuh, const int *vuhp, const double *vuhe, bool relvls, int numvls, const int *vlsp, const double *vlse, bool relvus, int numvus, const int *vusp, const double *vuse)
Set variable objects.
- void [assignVars](#) (int numRem, int *&posRem, int numAdd, [BcpsObject](#) **&objects, bool relvlh, int numvlh, int *&vlhp, double *&vlhe, bool relvuh, int numvuh, int *&vuhp, double *&vuhe, bool relvls, int numvls, int *&vlsp, double *&vlse, bool relvus, int numvus, int *&vusp, double *&vuse)
Assign variable objects.
- void [setCons](#) (int numRem, const int *posRem, int numAdd, const [BcpsObject](#) **objects, bool relclh, int numclh, const int *clhp, const double *clhe, bool relcuh, int numcuh, const int *cuhp, const double *cuhe, bool relcls, int numcls, const int *clsp, const double *clse, bool relcus, int numcus, const int *cusp, const double *cuse)
Set constraint objects.
- void [assignCons](#) (int numRem, int *&posRem, int numAdd, [BcpsObject](#) **&objects, bool relclh, int numclh, int *&clhp, double *&clhe, bool relcuh, int numcuh, int *&cuhp, double *&cuhe, bool relcls, int numcls, int *&clsp, double *&clse, bool relcus, int numcus, int *&cusp, double *&cuse)

- Assign constraint objects.*
- `BcpsObjectListMod * getVars () const`
- Get variable objects.*
- `BcpsObjectListMod * getCons () const`
- Get constraint objects.*
- `BcpsObjectListMod * vars ()`
- Accesss variables.*
- `BcpsObjectListMod * cons ()`
- Accesss constraints.*
- `void assignVarSoftBound (int numModSoftVarLB, int *&varLBi, double *&varLBv, int numModSoftVarUB, int *&varUBi, double *&varUBv)`
- Set variable soft bounds.*
- `void setVarSoftBound (int numModSoftVarLB, const int *varLBi, const double *varLBv, int numModSoftVarUB, const int *varUBi, const double *varUBv)`
- Set variable soft bounds.*
- `void assignVarHardBound (int numModHardVarLB, int *&varLBi, double *&varLBv, int numModHardVarUB, int *&varUBi, double *&varUBv)`
- Set variable hard bounds.*
- `void setConSoftBound (int numModSoftConLB, const int *conLBi, const double *conLBv, int numModSoftConUB, const int *conUBi, const double *conUBv)`
- Set constraint soft bounds.*
- `void setVarHardBound (int numModHardVarLB, const int *varLBi, const double *varLBv, int numModHardVarUB, const int *varUBi, const double *varUBv)`
- Set variable hard bounds.*
- `void setConHardBound (int numModHardConLB, const int *conLBi, const double *conLBv, int numModHardConUB, const int *conUBi, const double *conUBv)`
- Set constraint hard bounds.*
- `void appendAddedConstraints (int numAdd, BcpsObject **addCons)`
- Recode the added constraints.*
- `void setAddedConstraints (int numAdd, BcpsObject **addCons)`
- Recode the added constraints.*
- `void delConstraints (int numDel, int *indices)`
- Record the constraints are deleted.*
- `void addVariables (int numAdd, BcpsObject **addVars)`
- Record added variables.*
- `void delVariables (int numDel, int *indices)`
- Record deleted variables.*
- `AlpsReturnStatus encodeBcps (AlpsEncoded *encoded) const`
- Pack bcps node description into an encoded.*
- `AlpsReturnStatus decodeBcps (AlpsEncoded &encoded)`
- Unpack bcps node description into an encoded.*

Protected Member Functions

- `AlpsReturnStatus encodeDbfFieldMods (AlpsEncoded *encoded, BcpsFieldListMod< double > *field) const`
- Pack a double field into an encoded object.*
- `AlpsReturnStatus encodeIntFieldMods (AlpsEncoded *encoded, BcpsFieldListMod< int > *field) const`
- Pack a integer field into an encoded object.*

- AlpsReturnStatus [encodeObjectMods](#) (AlpsEncoded *encoded, [BcpsObjectListMod](#) *objMod) const
Pack object modifications to an encoded object.
- AlpsReturnStatus [decodeDbfFieldMods](#) (AlpsEncoded &encoded, [BcpsFieldListMod](#)< double > *field)
Unpack a double field from an encoded object.
- AlpsReturnStatus [decodeIntFieldMods](#) (AlpsEncoded &encoded, [BcpsFieldListMod](#)< int > *field)
Unpack a integer field from an encoded object.
- AlpsReturnStatus [decodeObjectMods](#) (AlpsEncoded &encoded, [BcpsObjectListMod](#) *objMod)
Unpack object modifications to an encoded object.

Protected Attributes

- [BcpsObjectListMod](#) * [vars_](#)
Variable objects.
- [BcpsObjectListMod](#) * [cons_](#)
Constraint objects.

3.8.1 Detailed Description

For a given type, the `objectVecStorage_` structure holds the description.

This description is explicit if the `numRemoved` member is -1. In this case, the `objects` member holds the full list of objects of the given type. If an explicit description of the parent is given together with a relative description of the current node then the process of reconstructing the explicit description of the current node is as follows:

1. initialize the explicit list **L** to be the parent's list;
2. remove the objects on the indicated positions from **L**;
3. modify the appropriate members of the objects in **L** according to the `vectorMod_` members of the `objectVecStorage_` structure;
4. append the objects to be added to **L**.

If the `numRemoved` field is -1, that means that the current description is explicit. In this case, the contents of the `vectorMod_` members are largely irrelevant, except for the `relative` fields which indicate whether the appropriate `vectorMod_` member can ever be expressed as a relative description or not.

If the `numRemoved` field is ≥ 0 , then the current description is considered relative even if every `vectorMod_` member contains explicit data. The description of a node can be either explicit or relative to its parent. In the node there are a number of object types and for each object type the explicit/relative description is considered separately.

If the information on an object type is relative, it means that at least one of the fields (`lbHard`, `ubHard`, etc.) has a relative description.

Definition at line 128 of file `BcpsNodeDesc.h`.

3.8.2 Constructor & Destructor Documentation

3.8.2.1 `BcpsNodeDesc::BcpsNodeDesc ()` `[inline]`

Default constructor.

Definition at line 141 of file `BcpsNodeDesc.h`.

3.8.2.2 BcpsNodeDesc::BcpsNodeDesc (BcpsModel * m) [inline]

Useful constructor.

Definition at line 144 of file BcpsNodeDesc.h.

3.8.2.3 virtual BcpsNodeDesc::~BcpsNodeDesc () [virtual]

Destructor.

3.8.3 Member Function Documentation

3.8.3.1 void BcpsNodeDesc::initToNull ()

Initialize member data.

3.8.3.2 void BcpsNodeDesc::setVars (int numRem, const int * posRem, int numAdd, const BcpsObject ** objects, bool relvlh, int numvlh, const int * vlhp, const double * vlhe, bool relvuh, int numvuh, const int * vuhp, const double * vuhe, bool relvls, int numvls, const int * vlsp, const double * vlse, bool relvus, int numvus, const int * vusp, const double * vuse)

Set variable objects.

3.8.3.3 void BcpsNodeDesc::assignVars (int numRem, int *& posRem, int numAdd, BcpsObject **& objects, bool relvlh, int numvlh, int *& vlhp, double *& vlhe, bool relvuh, int numvuh, int *& vuhp, double *& vuhe, bool relvls, int numvls, int *& vlsp, double *& vlse, bool relvus, int numvus, int *& vusp, double *& vuse)

Assign variable objects.

Take over memory ownership.

3.8.3.4 void BcpsNodeDesc::setCons (int numRem, const int * posRem, int numAdd, const BcpsObject ** objects, bool relclh, int numclh, const int * clhp, const double * clhe, bool relcuu, int numcuu, const int * cuhp, const double * cuhe, bool relcls, int numcls, const int * clsp, const double * clse, bool relcus, int numcus, const int * cusp, const double * cuse)

Set constraint objects.

3.8.3.5 void BcpsNodeDesc::assignCons (int numRem, int *& posRem, int numAdd, BcpsObject **& objects, bool relclh, int numclh, int *& clhp, double *& clhe, bool relcuu, int numcuu, int *& cuhp, double *& cuhe, bool relcls, int numcls, int *& clsp, double *& clse, bool relcus, int numcus, int *& cusp, double *& cuse)

Assign constraint objects.

Take over memory ownership.

3.8.3.6 BcpsObjectListMod* BcpsNodeDesc::getVars () const [inline]

Get variable objects.

Definition at line 243 of file BcpsNodeDesc.h.

3.8.3.7 BcpsObjectListMod* BcpsNodeDesc::getCons () const [inline]

Get constraint objects.

Definition at line 246 of file BcpsNodeDesc.h.

3.8.3.8 BcpsObjectListMod* BcpsNodeDesc::vars () [inline]

Accesss variables.

Definition at line 249 of file BcpsNodeDesc.h.

3.8.3.9 BcpsObjectListMod* BcpsNodeDesc::cons () [inline]

Accesss constraints.

Definition at line 252 of file BcpsNodeDesc.h.

3.8.3.10 void BcpsNodeDesc::assignVarSoftBound (int numModSoftVarLB, int *& varLBi, double *& varLBv, int numModSoftVarUB, int *& varUBi, double *& varUBv)

Set variable soft bounds.

Take ownerships of arraies.

3.8.3.11 void BcpsNodeDesc::setVarSoftBound (int numModSoftVarLB, const int * varLBi, const double * varLBv, int numModSoftVarUB, const int * varUBi, const double * varUBv)

Set variable soft bounds.

Don't take ownerships of arraies.

3.8.3.12 void BcpsNodeDesc::assignVarHardBound (int numModHardVarLB, int *& varLBi, double *& varLBv, int numModHardVarUB, int *& varUBi, double *& varUBv)

Set variable hard bounds.

Take ownerships of arraies.

3.8.3.13 void BcpsNodeDesc::setConSoftBound (int numModSoftConLB, const int * conLBi, const double * conLBv, int numModSoftConUB, const int * conUBi, const double * conUBv)

Set constraint soft bounds.

Don't take ownerships of arraies.

3.8.3.14 void BcpsNodeDesc::setVarHardBound (int numModHardVarLB, const int * varLBi, const double * varLBv, int numModHardVarUB, const int * varUBi, const double * varUBv)

Set variable hard bounds.

Don't take ownerships of arraies.

3.8.3.15 void BcpsNodeDesc::setConHardBound (int numModHardConLB, const int * conLBi, const double * conLBv, int numModHardConUB, const int * conUBi, const double * conUBv)

Set constraint hard bounds.

Don't take ownerships of arraies.

3.8.3.16 void BcpsNodeDesc::appendAddedConstraints (int numAdd, BcpsObject addCons) [inline]**

Recode the added constraints.

Take over the memory ownship of aguments. Append to previous constraints.

Definition at line 304 of file BcpsNodeDesc.h.

3.8.3.17 `void BcpsNodeDesc::setAddedConstraints (int numAdd, BcpsObject ** addCons) [inline]`

Recode the added constraints.

Take over the memory ownership of aguments. Delete already added constraints.

Definition at line 323 of file BcpsNodeDesc.h.

3.8.3.18 `void BcpsNodeDesc::delConstraints (int numDel, int * indices) [inline]`

Record the constraints are deleted.

Take over the memory ownership of arguments.

Definition at line 337 of file BcpsNodeDesc.h.

3.8.3.19 `void BcpsNodeDesc::addVariables (int numAdd, BcpsObject ** addVars) [inline]`

Record added variables.

Take over the memory ownership of arguments.

Definition at line 344 of file BcpsNodeDesc.h.

3.8.3.20 `void BcpsNodeDesc::delVariables (int numDel, int * indices) [inline]`

Record deleted variables.

Take over the memory ownership of arguemnts.

Definition at line 357 of file BcpsNodeDesc.h.

3.8.3.21 `AlpsReturnStatus BcpsNodeDesc::encodeDbiFieldMods (AlpsEncoded * encoded, BcpsFieldListMod< double > * field) const [protected]`

Pack a double field into an encoded object.

3.8.3.22 `AlpsReturnStatus BcpsNodeDesc::encodeIntFieldMods (AlpsEncoded * encoded, BcpsFieldListMod< int > * field) const [protected]`

Pack a integer field into an encoded object.

3.8.3.23 `AlpsReturnStatus BcpsNodeDesc::encodeObjectMods (AlpsEncoded * encoded, BcpsObjectListMod * objMod) const [protected]`

Pack object modifications to an encoded object.

3.8.3.24 `AlpsReturnStatus BcpsNodeDesc::decodeDbiFieldMods (AlpsEncoded & encoded, BcpsFieldListMod< double > * field) [protected]`

Unpack a double field from an encoded object.

3.8.3.25 `AlpsReturnStatus BcpsNodeDesc::decodeIntFieldMods (AlpsEncoded & encoded, BcpsFieldListMod< int > * field) [protected]`

Unpack a integer field from an encoded object.

3.8.3.26 `AlpsReturnStatus BcpsNodeDesc::decodeObjectMods (AlpsEncoded & encoded, BcpsObjectListMod * objMod) [protected]`

Unpack object modifications to an encoded object.

3.8.3.27 `AlpsResponseStatus BcpsNodeDesc::encodeBcps (AlpsEncoded * encoded) const`

Pack bcps node description into an encoded.

3.8.3.28 `AlpsResponseStatus BcpsNodeDesc::decodeBcps (AlpsEncoded & encoded)`

Unpack bcps node description into an encoded.

3.8.4 Member Data Documentation

3.8.4.1 `BcpsObjectListMod* BcpsNodeDesc::vars_ [protected]`

Variable objects.

Definition at line 133 of file BcpsNodeDesc.h.

3.8.4.2 `BcpsObjectListMod* BcpsNodeDesc::cons_ [protected]`

Constraint objects.

Definition at line 136 of file BcpsNodeDesc.h.

The documentation for this class was generated from the following file:

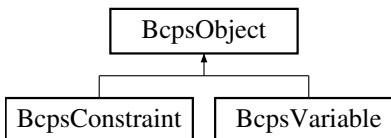
- BcpsNodeDesc.h

3.9 BcpsObject Class Reference

A class for describing the objects that comprise a BCPS subproblem.

```
#include <BcpsObject.h>
```

Inheritance diagram for BcpsObject:



Public Member Functions

- `BcpsObject` (const `BcpsObject` &rhs)
Copy constructor.
- `BcpsObject & operator=` (const `BcpsObject` &rhs)
Assignment operator.
- virtual `BcpsObject * clone` () const
Clone an entity.
- virtual double `infeasibility` (`BcpsModel` *m, int &preferredWay) const
Infeasibility of the object This is some measure of the infeasibility of the object.
- virtual void `feasibleRegion` (`BcpsModel` *m)
Look at the current solution and set bounds to match the solution.
- virtual `BcpsBranchObject * createBranchObject` (`BcpsModel` *m, int way) const

- Create a branching object and indicate which way to branch first.

 - virtual [BcpsBranchObject](#) * [preferredNewFeasible](#) ([BcpsModel](#) *m) const
Given a valid solution (with reduced costs, etc.), return a branching object which would give a new feasible point in a good direction.
 - virtual [BcpsBranchObject](#) * [notPreferredNewFeasible](#) ([BcpsModel](#) *m) const
Given a valid solution (with reduced costs, etc.), return a branching object which would give a new feasible point in a bad direction.
 - virtual void [resetBounds](#) ([BcpsModel](#) *m)
Reset variable bounds to their original values.
 - virtual bool [boundBranch](#) ([BcpsModel](#) *m) const
Return true if branches created by object will modify variable bounds.
 - virtual void [floorCeiling](#) (double &floorValue, double &ceilingValue, double value, double tolerance) const
Returns floor and ceiling i.e.
 - virtual double [upEstimate](#) () const
Return "up" estimate.
 - virtual double [downEstimate](#) () const
Return "down" estimate.
 - virtual AlpsReturnStatus [encode](#) (AlpsEncoded *encoded)
Pack into a encode object.
 - virtual AlpsKnowledge * [decode](#) (AlpsEncoded &encoded) const
Decode a constraint from an encoded object.
- int [getObjectIndex](#) () const
Return the value of the appropriate field.
- void [setObjectIndex](#) (int ind)
Set the appropriate property.
- virtual void [hashing](#) ([BcpsModel](#) *model=NULL)
Hashing.

Protected Member Functions

- AlpsReturnStatus [encodeBcpsObject](#) (AlpsEncoded *encoded) const
Pack Bcps part to a encode object.
- AlpsReturnStatus [decodeBcpsObject](#) (AlpsEncoded &encoded)
Unpack Bcps part from a encode object.

Protected Attributes

- int [objectIndex_](#)
Global index of this object.
- BcpsObjRep_t [repType_](#)
Core, indexed, or algorithmic.
- BcpsIntegral_t [intType_](#)
The integrality type of the object, i.e., what values it can take up between the specified bounds.
- BcpsValidRegion [validRegion_](#)

Valid in the whole tree or only the subtree rooted at the node that generate this object.

- int [status_](#)
The status of the object.
- double [lbHard_](#)
The lower bound of the object when it was first created.
- double [ubHard_](#)
The upper bound of the object when it was first created.
- double [lbSoft_](#)
The current lower bound of the object.
- double [ubSoft_](#)
The current upper bound of the object.
- double [hashValue_](#)
The hash value of this object.
- int [numInactive_](#)
Number of inactive when in formulation.
- double [effectiveness_](#)
Effectiveness: nonnegative value.

3.9.1 Detailed Description

A class for describing the objects that comprise a BCPS subproblem.

At the BCPS level, all that is assumed about an object is that it has bounds and that it has an integrality type. The concept that an object

Definition at line 76 of file BcpsObject.h.

3.9.2 Constructor & Destructor Documentation

3.9.2.1 BcpsObject::BcpsObject (const BcpsObject & rhs) [inline]

Copy constructor.

Definition at line 159 of file BcpsObject.h.

3.9.3 Member Function Documentation

3.9.3.1 BcpsObject& BcpsObject::operator= (const BcpsObject & rhs)

Assignment operator.

3.9.3.2 virtual BcpsObject* BcpsObject::clone () const [inline],[virtual]

Clone an entity.

Definition at line 178 of file BcpsObject.h.

3.9.3.3 virtual double BcpsObject::infeasibility (BcpsModel * m, int & preferredWay) const [inline],[virtual]

Infeasibility of the object This is some measure of the infeasibility of the object.

It should be scaled to be in the range [0.0, 0.5], with 0.0 indicating the object is satisfied.

The preferred branching direction is returned in preferredWay,

This is used to prepare for strong branching but should also think of case when no strong branching

The object may also compute an estimate of cost of going "up" or "down". This will probably be based on pseudo-cost ideas.

Definition at line 231 of file BcpsObject.h.

3.9.3.4 `virtual void BcpsObject::feasibleRegion (BcpsModel * m) [inline],[virtual]`

Look at the current solution and set bounds to match the solution.

Definition at line 236 of file BcpsObject.h.

3.9.3.5 `virtual BcpsBranchObject* BcpsObject::createBranchObject (BcpsModel * m, int way) const [inline],[virtual]`

Create a branching object and indicate which way to branch first.

The branching object has to know how to create branches (fix variables, etc.)

Definition at line 241 of file BcpsObject.h.

3.9.3.6 `virtual BcpsBranchObject* BcpsObject::preferredNewFeasible (BcpsModel * m) const [inline],[virtual]`

Given a valid solution (with reduced costs, etc.), return a branching object which would give a new feasible point in a good direction.

If the method cannot generate a feasible point (because there aren't any, or because it isn't bright enough to find one), it should return null.

Definition at line 252 of file BcpsObject.h.

3.9.3.7 `virtual BcpsBranchObject* BcpsObject::notPreferredNewFeasible (BcpsModel * m) const [inline],[virtual]`

Given a valid solution (with reduced costs, etc.), return a branching object which would give a new feasible point in a bad direction.

If the method cannot generate a feasible point (because there aren't any, or because it isn't bright enough to find one), it should return null.

Definition at line 263 of file BcpsObject.h.

3.9.3.8 `virtual void BcpsObject::resetBounds (BcpsModel * m) [inline],[virtual]`

Reset variable bounds to their original values.

Bounds may be tightened, so it may be good to be able to reset them to their original values.

Definition at line 271 of file BcpsObject.h.

3.9.3.9 `virtual bool BcpsObject::boundBranch (BcpsModel * m) const [inline],[virtual]`

Return true if branches created by object will modify variable bounds.

Definition at line 275 of file BcpsObject.h.

3.9.3.10 `virtual void BcpsObject::floorCeiling (double & floorValue, double & ceilingValue, double value, double tolerance) const` `[virtual]`

Returns floor and ceiling i.e.
closest valid points.

3.9.3.11 `virtual double BcpsObject::upEstimate () const` `[inline],[virtual]`

Return "up" estimate.

Default: 1.0e-5.

Definition at line 284 of file BcpsObject.h.

3.9.3.12 `virtual double BcpsObject::downEstimate () const` `[inline],[virtual]`

Return "down" estimate.

Default: 1.0e-5.

Definition at line 287 of file BcpsObject.h.

3.9.3.13 `AlpsReturnStatus BcpsObject::encodeBcpsObject (AlpsEncoded * encoded) const` `[inline],[protected]`

Pack Bcps part to a encode object.

Definition at line 294 of file BcpsObject.h.

3.9.3.14 `AlpsReturnStatus BcpsObject::decodeBcpsObject (AlpsEncoded & encoded)` `[inline],[protected]`

Unpack Bcps part from a encode object.

Definition at line 310 of file BcpsObject.h.

3.9.3.15 `virtual AlpsReturnStatus BcpsObject::encode (AlpsEncoded * encoded)` `[inline],[virtual]`

Pack into a encode object.

Definition at line 331 of file BcpsObject.h.

3.9.3.16 `virtual AlpsKnowledge* BcpsObject::decode (AlpsEncoded & encoded) const` `[inline],[virtual]`

Decode a constraint from an encoded object.

Definition at line 338 of file BcpsObject.h.

3.9.4 Member Data Documentation

3.9.4.1 `BcpsIntegral.t BcpsObject::intType_` `[protected]`

The integrality type of the object, i.e., what values it can take up between the specified bounds.

(Possible options: 'C' for continuous, 'I' for general integer, 'B' for binary and 'S' for semicontinuous)

Definition at line 90 of file BcpsObject.h.

3.9.4.2 `BcpsValidRegion BcpsObject::validRegion_` `[protected]`

Valid in the whole tree or only the subtree rooted at the node that generate this object.

Definition at line 94 of file BcpsObject.h.

3.9.4.3 `double BcpsObject::hashValue_` [protected]

The hash value of this object.

Definition at line 114 of file BcpsObject.h.

3.9.4.4 `int BcpsObject::numInactive_` [protected]

Number of inactive when in formulation.

Definition at line 117 of file BcpsObject.h.

3.9.4.5 `double BcpsObject::effectiveness_` [protected]

Effectiveness: nonnegative value.

Definition at line 120 of file BcpsObject.h.

The documentation for this class was generated from the following file:

- BcpsObject.h

3.10 BcpsObjectListMod Struct Reference

Here is the set of `vectorMod_` objects that represent the list of objects of a particular type (either in relative or explicit form).

```
#include <BcpsNodeDesc.h>
```

Public Attributes

- `int numRemove`
The number of entries to be deleted.
- `int * posRemove`
The positions of the entries to be deleted.
- `int numAdd`
The number of objects that are to be added.
- `BcpsObject ** objects`
The objects to be added.
- `BcpsFieldListMod< double > lbHard`
These are the data structures that store the changes in the individual fields.

3.10.1 Detailed Description

Here is the set of `vectorMod_` objects that represent the list of objects of a particular type (either in relative or explicit form).

If `numRemove` is positive, then `posRemove` contains the positions of the objects that are to be deleted from all the lists (that are stored relatively).

Definition at line 66 of file BcpsNodeDesc.h.

3.10.2 Member Data Documentation

3.10.2.1 `int BcpsObjectListMod::numRemove`

The number of entries to be deleted.

If this is -1, then all objects should be deleted, i.e., we have an explicit list.

Definition at line 70 of file BcpsNodeDesc.h.

3.10.2.2 `int* BcpsObjectListMod::posRemove`

The positions of the entries to be deleted.

Definition at line 73 of file BcpsNodeDesc.h.

3.10.2.3 `int BcpsObjectListMod::numAdd`

The number of objects that are to added.

Definition at line 76 of file BcpsNodeDesc.h.

3.10.2.4 `BcpsObject** BcpsObjectListMod::objects`

The objects to be added.

Definition at line 78 of file BcpsNodeDesc.h.

3.10.2.5 `BcpsFieldListMod<double> BcpsObjectListMod::lbHard`

These are the data structures that store the changes in the individual fields.

Definition at line 83 of file BcpsNodeDesc.h.

The documentation for this struct was generated from the following file:

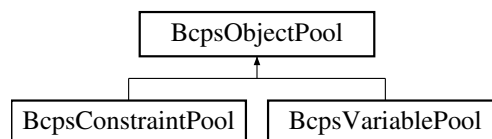
- BcpsNodeDesc.h

3.11 BcpsObjectPool Class Reference

Object pool is used to store objects.

```
#include <BcpsObjectPool.h>
```

Inheritance diagram for BcpsObjectPool:



Public Member Functions

- [BcpsObjectPool](#) ()
Default construct.
- void [freeGuts](#) ()

- Free object pointers.*

 - void `clear` ()

Reset to empty.
- virtual void `addKnowledge` (AlpsKnowledge *nk, double priority)

Add a knowledge to pool.
- virtual int `getNumKnowledges` () const

Query how many knowledges are in the pool.
- virtual std::pair
 < AlpsKnowledge *, double > `getKnowledge` () const

Query a knowledge, but doesn't remove it from the pool.
- virtual bool `hasKnowledge` () const

Check whether the pool has knowledge.
- void `deleteObject` (int k)

Delete object k from pool.
- const std::vector
 < AlpsKnowledge * > & `getObjects` () const

Get all objects.
- AlpsKnowledge * `getObject` (int k) const

Get a object.

3.11.1 Detailed Description

Object pool is used to store objects.

Definition at line 36 of file BcpsObjectPool.h.

3.11.2 Constructor & Destructor Documentation

3.11.2.1 BcpsObjectPool::BcpsObjectPool () [inline]

Default construct.

Definition at line 45 of file BcpsObjectPool.h.

3.11.3 Member Function Documentation

3.11.3.1 void BcpsObjectPool::freeGuts () [inline]

Free object pointers.

Definition at line 53 of file BcpsObjectPool.h.

3.11.3.2 void BcpsObjectPool::clear () [inline]

Reset to empty.

Don't free memory.

Definition at line 61 of file BcpsObjectPool.h.

3.11.3.3 `virtual int BcpsObjectPool::getNumKnowledges () const [inline],[virtual]`

Query how many knowledges are in the pool.

Definition at line 69 of file BcpsObjectPool.h.

3.11.3.4 `virtual bool BcpsObjectPool::hasKnowledge () const [inline],[virtual]`

Check whether the pool has knowledge.

Definition at line 79 of file BcpsObjectPool.h.

3.11.3.5 `const std::vector<AlpsKnowledge*>& BcpsObjectPool::getObjects () const [inline]`

Get all objects.

Definition at line 96 of file BcpsObjectPool.h.

3.11.3.6 `AlpsKnowledge* BcpsObjectPool::getObject (int k) const [inline]`

Get a object.

Definition at line 99 of file BcpsObjectPool.h.

The documentation for this class was generated from the following file:

- BcpsObjectPool.h

3.12 BcpsSolution Class Reference

This class holds the solution objects.

```
#include <BcpsSolution.h>
```

Public Member Functions

- [BcpsSolution](#) ()
Default constructor.
- [BcpsSolution](#) (int size, const double *values, double q)
Useful constructor.
- [BcpsSolution](#) (int size, [BcpsObject_p](#) *&objects, double *&values, double q)
Construct an object using the given arrays.
- virtual [~BcpsSolution](#) ()
Distructor.
- virtual void [print](#) (std::ostream &os) const
Print out the solution.
- AlpsReturnStatus [encodeBcps](#) (AlpsEncoded *encoded) const
Pack Bcps part of solution into an encoded objects.
- AlpsReturnStatus [decodeBcps](#) (AlpsEncoded &encoded)
Unpack Bcps part of solution from an encoded objects.
- int [getSize](#) () const
Get the appropriate data member.

- void `setSize` (int s)
Set/assign the appropriate data member.
- virtual `BcpsSolution * selectNonzeros` (const double etol=1e-5) const
Select the fractional/nonzero elements from the solution array and return a new object in compacted form.

Protected Attributes

- int `size_`
Size of values_.
- `BcpsObject_p * objects_`
List of objects associated with values.
- double * `values_`
Solution values.
- double `quality_`
Quality/Objective value associated with this solution.

3.12.1 Detailed Description

This class holds the solution objects.

At this level, a solution is just considered to be a list of objects with associated values.

Definition at line 34 of file BcpsSolution.h.

3.12.2 Constructor & Destructor Documentation

3.12.2.1 BcpsSolution::BcpsSolution () [inline]

Default constructor.

Definition at line 58 of file BcpsSolution.h.

3.12.2.2 BcpsSolution::BcpsSolution (int size, const double * values, double q) [inline]

Useful constructor.

Definition at line 64 of file BcpsSolution.h.

3.12.2.3 BcpsSolution::BcpsSolution (int size, BcpsObject_p *& objects, double *& values, double q) [inline]

Construct an object using the given arrays.

Note that the new objects takes over the pointers and NULLs them out in the calling method.

Definition at line 80 of file BcpsSolution.h.

3.12.2.4 virtual BcpsSolution::~~BcpsSolution () [inline], [virtual]

Distructor.

Definition at line 88 of file BcpsSolution.h.

3.12.3 Member Function Documentation

3.12.3.1 `int BcpsSolution::getSize () const [inline]`

Get the appropriate data member.

Definition at line 100 of file BcpsSolution.h.

3.12.3.2 `void BcpsSolution::setSize (int s) [inline]`

Set/assign the appropriate data member.

Definition at line 108 of file BcpsSolution.h.

3.12.3.3 `virtual BcpsSolution* BcpsSolution::selectNonzeros (const double etol = 1e-5) const [virtual]`

Select the fractional/nonzero elements from the solution array and return a new object in compacted form.

3.12.3.4 `virtual void BcpsSolution::print (std::ostream & os) const [inline], [virtual]`

Print out the solution.

Definition at line 130 of file BcpsSolution.h.

3.12.3.5 `AlpsReturnStatus BcpsSolution::encodeBcps (AlpsEncoded * encoded) const`

Pack Bcps part of solution into an encoded objects.

3.12.3.6 `AlpsReturnStatus BcpsSolution::decodeBcps (AlpsEncoded & encoded)`

Unpack Bcps part of solution from an encoded objects.

3.12.4 Member Data Documentation

3.12.4.1 `int BcpsSolution::size_ [protected]`

Size of values_.

Definition at line 44 of file BcpsSolution.h.

3.12.4.2 `BcpsObject_p* BcpsSolution::objects_ [protected]`

List of objects associated with values.

Can be NULL.

Definition at line 47 of file BcpsSolution.h.

3.12.4.3 `double* BcpsSolution::values_ [protected]`

Solution values.

Definition at line 50 of file BcpsSolution.h.

3.12.4.4 `double BcpsSolution::quality_ [protected]`

Quality/Objective value associated with this solution.

Definition at line 53 of file BcpsSolution.h.

The documentation for this class was generated from the following file:

- BcpsSolution.h

3.13 BcpsSubTree Class Reference

This class is the data structure for storing a subtree within BCPS.

```
#include <BcpsSubTree.h>
```

3.13.1 Detailed Description

This class is the data structure for storing a subtree within BCPS.

The biggest addition to the fields that already exist withink ALPS is the storage for the global list of objects that are active within that subtree. Initially, this will be implemeted as a `std::set`, but later on should be changed to something more efficient such as a hash table or something like that.

Definition at line 42 of file BcpsSubTree.h.

The documentation for this class was generated from the following file:

- BcpsSubTree.h

3.14 BcpsTreeNode Class Reference

This class contain the data for a BCPS search tree node.

```
#include <BcpsTreeNode.h>
```

Public Member Functions

- [BcpsTreeNode](#) ()
Default constructor.
- virtual [~BcpsTreeNode](#) ()
Destructor.
- virtual int [process](#) (bool isRoot=false, bool rampUp=false)
This methods performs the processing of the node.
- virtual int [bound](#) ([BcpsModel](#) *model)=0
Bounding procedure to estimate quality of this node.
- virtual std::vector
< [CoinTriple](#)< [AlpsNodeDesc](#)
, [AlpsNodeStatus](#), double > > [branch](#) ()=0
*This method must be invoked on a *pregnant* node (which has all the information needed to create the children) and should create the children's decriptions.*
- const [BcpsBranchObject](#) * [branchObject](#) () const
Return the branching object.
- void [setBranchObject](#) ([BcpsBranchObject](#) *b)
Set the branching object.

Protected Member Functions

- virtual int [generateConstraints](#) (BcpsModel *model, BcpsConstraintPool *conPool)
Generate constraints.
- virtual int [generateVariables](#) (BcpsModel *model, BcpsVariablePool *varPool)
Generate variables.
- virtual int [chooseBranchingObject](#) (BcpsModel *model)=0
Choose a branching object.
- virtual int [installSubProblem](#) (BcpsModel *model)=0
Extract node information (bounds, constraints, variables) from this node and load the information into the relaxation solver, such as linear programming solver.
- virtual int [handleBoundingStatus](#) (int status, bool &keepOn, bool &fathomed)
Handle bounding status:
- AlpsReturnStatus [encodeBcps](#) (AlpsEncoded *encoded) const
Pack Bcps portion of node into an encoded object.

Protected Attributes

- BcpsBranchObject * [branchObject_](#)
Branching object for this node, which has information of how to execute branching.

3.14.1 Detailed Description

This class contain the data for a BCPS search tree node.

At this level, we consider a tree node to be simply a list of objects. The objects are organized by type. A differencing scheme is implemented here by looking for differences between the lists of each type in the current node and its parent.

Definition at line 46 of file BcpsTreeNode.h.

3.14.2 Constructor & Destructor Documentation

3.14.2.1 BcpsTreeNode::BcpsTreeNode () [inline]

Default constructor.

Definition at line 99 of file BcpsTreeNode.h.

3.14.2.2 virtual BcpsTreeNode::~BcpsTreeNode () [inline], [virtual]

Destructor.

Definition at line 102 of file BcpsTreeNode.h.

3.14.3 Member Function Documentation

3.14.3.1 virtual int BcpsTreeNode::generateConstraints (BcpsModel * model, BcpsConstraintPool * conPool) [inline], [protected], [virtual]

Generate constraints.

The generated constraints are stored in constraint pool. The default implementation does nothing.

Definition at line 58 of file BcpsTreeNode.h.

3.14.3.2 `virtual int BcpsTreeNode::generateVariables (BcpsModel * model, BcpsVariablePool * varPool) [inline], [protected], [virtual]`

Generate variables.

The generated variables are stored in variable pool. The default implementation does nothing.

Definition at line 66 of file BcpsTreeNode.h.

3.14.3.3 `virtual int BcpsTreeNode::chooseBranchingObject (BcpsModel * model) [protected], [pure virtual]`

Choose a branching object.

3.14.3.4 `virtual int BcpsTreeNode::installSubProblem (BcpsModel * model) [protected], [pure virtual]`

Extract node information (bounds, constraints, variables) from this node and load the information into the relaxation solver, such as linear programming solver.

3.14.3.5 `virtual int BcpsTreeNode::handleBoundingStatus (int status, bool & keepOn, bool & fathomed) [inline], [protected], [virtual]`

Handle bounding status:

- relaxed feasible but not integer feasible,
- integer feasible,
- infeasible,
- unbounded,
- fathomed (for instance, reaching objective limit for LP). Set node status accordingly.

Parameters

| | |
|-----------------|--|
| <i>staus</i> | Input The solution status of bounding. |
| <i>keepOn</i> | Output Whether to keep on bounding. |
| <i>fathomed</i> | Output Whether this node is fathomed. |

Definition at line 91 of file BcpsTreeNode.h.

3.14.3.6 `virtual int BcpsTreeNode::process (bool isRoot = false, bool rampUp = false) [virtual]`

This methods performs the processing of the node.

For branch and bound, this would mean performing the bounding operation. The minimum requirement for this method is that it change the status to either internal or fathomed so the tree manager can deal with it afterwards. The status of the node when it begins processing will be active.

3.14.3.7 `virtual int BcpsTreeNode::bound (BcpsModel * model) [pure virtual]`

Bounding procedure to estimate quality of this node.

3.14.3.8 `virtual std::vector< CoinTriple<AlpsNodeDesc*, AlpsNodeStatus, double> > BcpsTreeNode::branch () [pure virtual]`

This method must be invoked on a `pregnant` node (which has all the information needed to create the children) and should create the children's decriptions.

The stati of the children can be any of the ones `process()` can return.

3.14.3.9 `const BcpsBranchObject* BcpsTreeNode::branchObject () const` `[inline]`

Return the branching object.

Definition at line 123 of file BcpsTreeNode.h.

3.14.3.10 `void BcpsTreeNode::setBranchObject (BcpsBranchObject * b)` `[inline]`

Set the branching object.

Definition at line 126 of file BcpsTreeNode.h.

3.14.3.11 `AlpsReturnStatus BcpsTreeNode::encodeBcps (AlpsEncoded * encoded) const` `[inline], [protected]`

Pack Bcps portion of node into an encoded object.

Definition at line 131 of file BcpsTreeNode.h.

3.14.4 Member Data Documentation

3.14.4.1 `BcpsBranchObject* BcpsTreeNode::branchObject_` `[protected]`

Branching object for this node, which has information of how to execute branching.

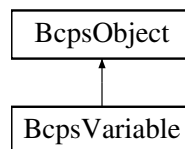
Definition at line 52 of file BcpsTreeNode.h.

The documentation for this class was generated from the following file:

- BcpsTreeNode.h

3.15 BcpsVariable Class Reference

Inheritance diagram for BcpsVariable:



Public Member Functions

- [BcpsVariable](#) ()
Default constructor.
- [BcpsVariable](#) (double lbh, double ubh, double lbs, double ubs)
Useful constructor.
- virtual [~BcpsVariable](#) ()
Destructor.
- [BcpsVariable](#) (const [BcpsVariable](#) &rhs)
Copy constructor.

Additional Inherited Members

3.15.1 Detailed Description

Definition at line 383 of file BcpsObject.h.

3.15.2 Constructor & Destructor Documentation

3.15.2.1 BcpsVariable::BcpsVariable () [inline]

Default constructor.

Definition at line 386 of file BcpsObject.h.

3.15.2.2 BcpsVariable::BcpsVariable (double lbh, double ubh, double lbs, double ub) [inline]

Useful constructor.

Definition at line 389 of file BcpsObject.h.

3.15.2.3 virtual BcpsVariable::~~BcpsVariable () [inline],[virtual]

Destructor.

Definition at line 395 of file BcpsObject.h.

3.15.2.4 BcpsVariable::BcpsVariable (const BcpsVariable & rhs) [inline]

Copy constructor.

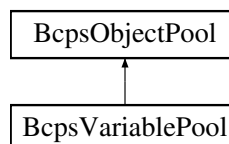
Definition at line 398 of file BcpsObject.h.

The documentation for this class was generated from the following file:

- BcpsObject.h

3.16 BcpsVariablePool Class Reference

Inheritance diagram for BcpsVariablePool:



Public Member Functions

- void [addVariable](#) ([BcpsVariable](#) *var)
Add a variable to pool.
- void [deleteVariable](#) (int k)
Delete variable k from pool.
- int [getNumVariables](#) () const
Query how many variables are in the pool.

- `const std::vector< AlpsKnowledge * > & getVariables () const`
Get the vector of variables.
- `AlpsKnowledge * getVariable (int k) const`
Get the vector of variables.

3.16.1 Detailed Description

Definition at line 127 of file BcpsObjectPool.h.

3.16.2 Member Function Documentation

3.16.2.1 `int BcpsVariablePool::getNumVariables () const` [inline]

Query how many variables are in the pool.

Definition at line 139 of file BcpsObjectPool.h.

3.16.2.2 `const std::vector<AlpsKnowledge *>& BcpsVariablePool::getVariables () const` [inline]

Get the vector of variables.

Definition at line 142 of file BcpsObjectPool.h.

3.16.2.3 `AlpsKnowledge* BcpsVariablePool::getVariable (int k) const` [inline]

Get the vector of variables.

Definition at line 145 of file BcpsObjectPool.h.

The documentation for this class was generated from the following file:

- BcpsObjectPool.h

Index

- ~BcpsBranchObject
 - BcpsBranchObject, 5
- ~BcpsBranchStrategy
 - BcpsBranchStrategy, 10
- ~BcpsConstraint
 - BcpsConstraint, 13
- ~BcpsNodeDesc
 - BcpsNodeDesc, 21
- ~BcpsSolution
 - BcpsSolution, 33
- ~BcpsTreeNode
 - BcpsTreeNode, 36
- ~BcpsVariable
 - BcpsVariable, 39
- addVariables
 - BcpsNodeDesc, 23
- appendAddedConstraints
 - BcpsNodeDesc, 22
- assignCons
 - BcpsNodeDesc, 21
- assignVarHardBound
 - BcpsNodeDesc, 22
- assignVarSoftBound
 - BcpsNodeDesc, 22
- assignVars
 - BcpsNodeDesc, 21
- BcpsBranchObject, 3
 - ~BcpsBranchObject, 5
 - BcpsBranchObject, 5
 - BcpsBranchObject, 5
 - boundBranch, 6
 - branch, 6
 - clone, 5
 - decode, 7
 - decodeBcps, 7
 - direction_, 8
 - downScore_, 8
 - encode, 7
 - encodeBcps, 7
 - getDirection, 7
 - getDownScore, 7
 - getObjectIndex, 6
 - getType, 5
 - getUpScore, 6
 - getValue, 7
 - model, 7
 - model_, 8
 - numBranches, 6
 - numBranchesLeft, 6
 - numBranchesLeft_, 8
 - objectIndex_, 8
 - operator=, 5
 - print, 6
 - setDirection, 7
 - setDownScore, 7
 - setObjectIndex, 6
 - setType, 6
 - setUpScore, 6
 - type_, 8
 - upScore_, 8
 - value_, 8
- BcpsBranchStrategy, 9
 - ~BcpsBranchStrategy, 10
 - BcpsBranchStrategy, 10
 - BcpsBranchStrategy, 10
 - bestBranchObject, 11
 - bestBranchObject_, 12
 - bestChangeDown_, 12
 - bestChangeUp_, 12
 - bestNumberDown_, 12
 - bestNumberUp_, 12
 - betterBranchObject, 11
 - branchObjects_, 12
 - clearBest, 11
 - clone, 11
 - createCandBranchObjects, 11
 - getNumBranchObjects, 11
 - getType, 11
 - model_, 12
 - numBranchObjects_, 12
 - setModel, 11
 - setType, 11
 - type_, 11
- BcpsConstraint, 13
 - ~BcpsConstraint, 13
 - BcpsConstraint, 13
 - BcpsConstraint, 13
- BcpsConstraintPool, 14
 - getConstraint, 14
 - getConstraints, 14
 - getNumConstraints, 14
- BcpsFieldListMod
 - numModify, 15
 - posModify, 15
- BcpsFieldListMod< T >, 15
- BcpsMessage, 15
- bcpsMessageHandler
 - BcpsModel, 17
- bcpsMessageHandler_
 - BcpsModel, 18
- bcpsMessages

- BcpsModel, 17
- bcpsMessages_
 - BcpsModel, 18
- BcpsModel, 16
 - bcpsMessageHandler, 17
 - bcpsMessageHandler_, 18
 - bcpsMessages, 17
 - bcpsMessages_, 18
 - constraints_, 17
 - decodeBcps, 17
 - encodeBcps, 17
 - getConstrints, 17
 - getVariables, 17
 - numCoreConstraints_, 17
 - numCoreVariables_, 17
 - variables_, 17
- BcpsNodeDesc, 18
 - ~BcpsNodeDesc, 21
 - addVariables, 23
 - appendAddedConstraints, 22
 - assignCons, 21
 - assignVarHardBound, 22
 - assignVarSoftBound, 22
 - assignVars, 21
 - BcpsNodeDesc, 20
 - BcpsNodeDesc, 20
 - cons, 22
 - cons_, 24
 - decodeBcps, 24
 - decodeDbfFieldMods, 23
 - decodeIntFieldMods, 23
 - decodeObjectMods, 23
 - delConstraints, 23
 - delVariables, 23
 - encodeBcps, 23
 - encodeDbfFieldMods, 23
 - encodeIntFieldMods, 23
 - encodeObjectMods, 23
 - getCons, 21
 - getVars, 21
 - initToNull, 21
 - setAddedConstraints, 22
 - setConHardBound, 22
 - setConSoftBound, 22
 - setCons, 21
 - setVarHardBound, 22
 - setVarSoftBound, 22
 - setVars, 21
 - vars, 21
 - vars_, 24
- BcpsObject, 24
 - BcpsObject, 26
 - BcpsObject, 26
 - boundBranch, 27
 - clone, 26
 - createBranchObject, 27
 - decode, 28
 - decodeBcpsObject, 28
 - downEstimate, 28
 - effectiveness_, 29
 - encode, 28
 - encodeBcpsObject, 28
 - feasibleRegion, 27
 - floorCeiling, 27
 - hashValue_, 28
 - infeasibility, 26
 - intType_, 28
 - notPreferredNewFeasible, 27
 - numInactive_, 29
 - operator=, 26
 - preferredNewFeasible, 27
 - resetBounds, 27
 - upEstimate, 28
 - validRegion_, 28
- BcpsObjectListMod, 29
 - lbHard, 30
 - numAdd, 30
 - numRemove, 30
 - objects, 30
 - posRemove, 30
- BcpsObjectPool, 30
 - BcpsObjectPool, 31
 - BcpsObjectPool, 31
 - clear, 31
 - freeGuts, 31
 - getNumKnowledges, 31
 - getObject, 32
 - getObjects, 32
 - hasKnowledge, 32
- BcpsSolution, 32
 - ~BcpsSolution, 33
 - BcpsSolution, 33
 - BcpsSolution, 33
 - decodeBcps, 34
 - encodeBcps, 34
 - getSize, 34
 - objects_, 34
 - print, 34
 - quality_, 34
 - selectNonzeros, 34
 - setSize, 34
 - size_, 34
 - values_, 34
- BcpsSubTree, 35
- BcpsTreeNode, 35
 - ~BcpsTreeNode, 36
 - BcpsTreeNode, 36
 - BcpsTreeNode, 36

- bound, [37](#)
- branch, [37](#)
- branchObject, [37](#)
- branchObject_, [38](#)
- chooseBranchingObject, [37](#)
- encodeBcps, [38](#)
- generateConstraints, [36](#)
- generateVariables, [36](#)
- handleBoundingStatus, [37](#)
- installSubProblem, [37](#)
- process, [37](#)
- setBranchObject, [38](#)
- BcpsVariable, [38](#)
 - ~BcpsVariable, [39](#)
 - BcpsVariable, [39](#)
 - BcpsVariable, [39](#)
- BcpsVariablePool, [39](#)
 - getNumVariables, [40](#)
 - getVariable, [40](#)
 - getVariables, [40](#)
- bestBranchObject
 - BcpsBranchStrategy, [11](#)
- bestBranchObject_
 - BcpsBranchStrategy, [12](#)
- bestChangeDown_
 - BcpsBranchStrategy, [12](#)
- bestChangeUp_
 - BcpsBranchStrategy, [12](#)
- bestNumberDown_
 - BcpsBranchStrategy, [12](#)
- bestNumberUp_
 - BcpsBranchStrategy, [12](#)
- betterBranchObject
 - BcpsBranchStrategy, [11](#)
- bound
 - BcpsTreeNode, [37](#)
- boundBranch
 - BcpsBranchObject, [6](#)
 - BcpsObject, [27](#)
- branch
 - BcpsBranchObject, [6](#)
 - BcpsTreeNode, [37](#)
- branchObject
 - BcpsTreeNode, [37](#)
- branchObject_
 - BcpsTreeNode, [38](#)
- branchObjects_
 - BcpsBranchStrategy, [12](#)
- chooseBranchingObject
 - BcpsTreeNode, [37](#)
- clear
 - BcpsObjectPool, [31](#)
- clearBest
 - BcpsBranchStrategy, [11](#)
- clone
 - BcpsBranchObject, [5](#)
 - BcpsBranchStrategy, [11](#)
 - BcpsObject, [26](#)
- cons
 - BcpsNodeDesc, [22](#)
- cons_
 - BcpsNodeDesc, [24](#)
- constraints_
 - BcpsModel, [17](#)
- createBranchObject
 - BcpsObject, [27](#)
- createCandBranchObjects
 - BcpsBranchStrategy, [11](#)
- decode
 - BcpsBranchObject, [7](#)
 - BcpsObject, [28](#)
- decodeBcps
 - BcpsBranchObject, [7](#)
 - BcpsModel, [17](#)
 - BcpsNodeDesc, [24](#)
 - BcpsSolution, [34](#)
- decodeBcpsObject
 - BcpsObject, [28](#)
- decodeDbfFieldMods
 - BcpsNodeDesc, [23](#)
- decodeIntFieldMods
 - BcpsNodeDesc, [23](#)
- decodeObjectMods
 - BcpsNodeDesc, [23](#)
- delConstraints
 - BcpsNodeDesc, [23](#)
- delVariables
 - BcpsNodeDesc, [23](#)
- direction_
 - BcpsBranchObject, [8](#)
- downEstimate
 - BcpsObject, [28](#)
- downScore_
 - BcpsBranchObject, [8](#)
- effectiveness_
 - BcpsObject, [29](#)
- encode
 - BcpsBranchObject, [7](#)
 - BcpsObject, [28](#)
- encodeBcps
 - BcpsBranchObject, [7](#)
 - BcpsModel, [17](#)
 - BcpsNodeDesc, [23](#)
 - BcpsSolution, [34](#)
 - BcpsTreeNode, [38](#)
- encodeBcpsObject

- BcpsObject, 28
- encodeDbfFieldMods
 - BcpsNodeDesc, 23
- encodeIntFieldMods
 - BcpsNodeDesc, 23
- encodeObjectMods
 - BcpsNodeDesc, 23
- feasibleRegion
 - BcpsObject, 27
- floorCeiling
 - BcpsObject, 27
- freeGuts
 - BcpsObjectPool, 31
- generateConstraints
 - BcpsTreeNode, 36
- generateVariables
 - BcpsTreeNode, 36
- getCons
 - BcpsNodeDesc, 21
- getConstraint
 - BcpsConstraintPool, 14
- getConstraints
 - BcpsConstraintPool, 14
- getConstraints
 - BcpsModel, 17
- getDirection
 - BcpsBranchObject, 7
- getDownScore
 - BcpsBranchObject, 7
- getNumBranchObjects
 - BcpsBranchStrategy, 11
- getNumConstraints
 - BcpsConstraintPool, 14
- getNumKnowledges
 - BcpsObjectPool, 31
- getNumVariables
 - BcpsVariablePool, 40
- getObject
 - BcpsObjectPool, 32
- getObjectIndex
 - BcpsBranchObject, 6
- getObjects
 - BcpsObjectPool, 32
- getSize
 - BcpsSolution, 34
- getType
 - BcpsBranchObject, 5
 - BcpsBranchStrategy, 11
- getUpScore
 - BcpsBranchObject, 6
- getValue
 - BcpsBranchObject, 7
- getVariable
 - BcpsVariablePool, 40
- getVariables
 - BcpsModel, 17
 - BcpsVariablePool, 40
- getVars
 - BcpsNodeDesc, 21
- handleBoundingStatus
 - BcpsTreeNode, 37
- hasKnowledge
 - BcpsObjectPool, 32
- hashValue_
 - BcpsObject, 28
- infeasibility
 - BcpsObject, 26
- initToNull
 - BcpsNodeDesc, 21
- installSubProblem
 - BcpsTreeNode, 37
- intType_
 - BcpsObject, 28
- lbHard
 - BcpsObjectListMod, 30
- model
 - BcpsBranchObject, 7
- model_
 - BcpsBranchObject, 8
 - BcpsBranchStrategy, 12
- notPreferredNewFeasible
 - BcpsObject, 27
- numAdd
 - BcpsObjectListMod, 30
- numBranchObjects_
 - BcpsBranchStrategy, 12
- numBranches
 - BcpsBranchObject, 6
- numBranchesLeft
 - BcpsBranchObject, 6
- numBranchesLeft_
 - BcpsBranchObject, 8
- numCoreConstraints_
 - BcpsModel, 17
- numCoreVariables_
 - BcpsModel, 17
- numInactive_
 - BcpsObject, 29
- numModify
 - BcpsFieldListMod, 15
- numRemove
 - BcpsObjectListMod, 30
- objectIndex_

- BcpsBranchObject, [8](#)
- objects
 - BcpsObjectListMod, [30](#)
- objects_
 - BcpsSolution, [34](#)
- operator=
 - BcpsBranchObject, [5](#)
 - BcpsObject, [26](#)
- posModify
 - BcpsFieldListMod, [15](#)
- posRemove
 - BcpsObjectListMod, [30](#)
- preferredNewFeasible
 - BcpsObject, [27](#)
- print
 - BcpsBranchObject, [6](#)
 - BcpsSolution, [34](#)
- process
 - BcpsTreeNode, [37](#)
- quality_
 - BcpsSolution, [34](#)
- resetBounds
 - BcpsObject, [27](#)
- selectNonzeros
 - BcpsSolution, [34](#)
- setAddedConstraints
 - BcpsNodeDesc, [22](#)
- setBranchObject
 - BcpsTreeNode, [38](#)
- setConHardBound
 - BcpsNodeDesc, [22](#)
- setConSoftBound
 - BcpsNodeDesc, [22](#)
- setCons
 - BcpsNodeDesc, [21](#)
- setDirection
 - BcpsBranchObject, [7](#)
- setDownScore
 - BcpsBranchObject, [7](#)
- setModel
 - BcpsBranchStrategy, [11](#)
- setObjectIndex
 - BcpsBranchObject, [6](#)
- setSize
 - BcpsSolution, [34](#)
- setType
 - BcpsBranchObject, [6](#)
 - BcpsBranchStrategy, [11](#)
- setUpScore
 - BcpsBranchObject, [6](#)
- setVarHardBound
 - BcpsNodeDesc, [22](#)
- setVarSoftBound
 - BcpsNodeDesc, [22](#)
- setVars
 - BcpsNodeDesc, [21](#)
- size_
 - BcpsSolution, [34](#)
- type_
 - BcpsBranchObject, [8](#)
 - BcpsBranchStrategy, [11](#)
- upEstimate
 - BcpsObject, [28](#)
- upScore_
 - BcpsBranchObject, [8](#)
- validRegion_
 - BcpsObject, [28](#)
- value_
 - BcpsBranchObject, [8](#)
- values_
 - BcpsSolution, [34](#)
- variables_
 - BcpsModel, [17](#)
- vars
 - BcpsNodeDesc, [21](#)
- vars_
 - BcpsNodeDesc, [24](#)