

**DALHOUSIE
UNIVERSITY**

Inspiring Minds

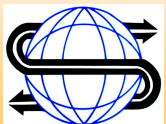
OSiL: An XML-based schema for stochastic programs

H.I. Gassmann, R. Fourer, J. Ma, R.K. Martin

SP XI Vienna, August 2007

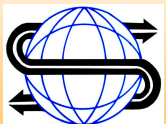
Outline

- Motivation and review
- A four-stage investment problem
- OSiL format
- Conclusions and future work



Why a standard?

- Benchmarking
- Archiving
- Algorithm development
- Distributed computing
- Sharing of problem instances



Why XML?

- Existing parsers to check syntax
- Easy to generate automatically
- Tree structure naturally mirrors expression trees for nonlinear functions
- Arbitrary precision and name space
- Automatic attribute checking (e.g., nonnegativity)
- Querying capabilities via XQuery
- Encryption standards being developed
- Easy integration into broader IT infrastructure



Stochastic programs

$$\begin{array}{ll}
 \min & f_0(x_0) + f_1(x_0, x_1) + \dots + f_T(x_0, x_1, \dots, x_T) \\
 \text{“ s.t.,”} & G_0(x_0) \sim b_0 \\
 & R_1(x_0) \Delta r_1 \\
 & G_1(x_0, x_1) \Delta b_1 \\
 & \vdots \\
 & G_T(x_0, x_1, \dots, x_T) \Delta b_T \\
 & l_0 \leq x_0 \leq u_0 \\
 & l_t \leq x_t \leq u_t, t = 1, \dots, T
 \end{array}$$

Any data item with nonzero subscript may be random (including dimensions where mathematically sensible)

~ stands for arbitrary relations ($\leq, =, \geq$)

Δ means ~ with probability 1

or with probability at least β

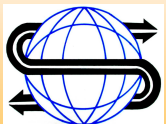
or with expected violation at most v

or ... © 2007 H.I. Gassmann



Problem classes and time domain

- Single-stage problems
 - Mean-variance problems (Markowitz)
 - Robust optimization
 - Chance-constrained problems
 - Reformulated and solved as deterministic nonlinear problems



Problem classes and time domain (cont'd)

- Two-stage problems with recourse
 - Solved by
 - Deterministic equivalent methods
 - Benders decomposition
 - Stochastic quasigradient methods
 - Stochastic decomposition (Higle and Sen)
 - Monte Carlo sampling (Shapiro and Homem-de-Mello)
 - Regression approximation (Deák)
 - Distributions
 - Known
 - Approximated (by scenario generation)
 - Partially known (moments, distribution type, support, etc.)



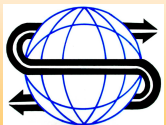
Problem classes and time domain (cont'd)

- Multi-stage recourse models
 - Deterministic equivalent
 - Nested Benders decomposition
 - Progressive hedging
 - Multistage stochastic decomposition
 - Probabilistic constraints and risk measures can be added as “linking constraints”



Problem classes and time domain (cont'd)

- Horizon problems (Grinold, Sethi)
- Markov reward processes
- Continuous time problems



Example (Birge)

$$\max \sum_{s=1}^S p_s (w_s - \beta u_s)$$

$$\text{s.t. } \sum_{i=1}^I x_{0i}$$

$$= B$$

$$\sum_{i=1}^I \alpha_{0is} x_{0i} - \sum_{i=1}^I x_{1is}$$

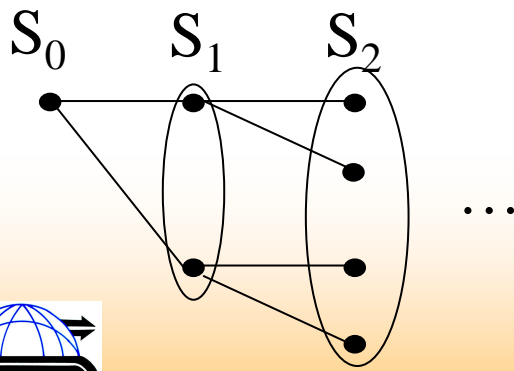
$$= 0, s \in S_1$$

$$\sum_{i=1}^I \alpha_{t-1,i,s} x_{t-1,i,a(s)} - \sum_{i=1}^I x_{tis}$$

$$= 0, s \in S_t, t = 2, \dots, T-1$$

$$\sum_{i=1}^I \alpha_{T-1,i,s} x_{T-1,i,a(s)} + u_s - w_s = R, s \in S_T$$

$$x_{tis}, u_s, w_s \geq 0$$



$$I = 2, T = 3, B = 55, R = 80,$$

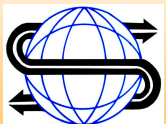
$$\alpha_{t1} = \{1.25, 1.06\},$$

$$\alpha_{t2} = \{1.14, 1.12\}$$



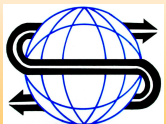
Markup languages

- Intersperse text (data) and information about it (formatting, etc.)
- Examples
 - TeX (extensible through user \def)
 - HTML
 - VRML
 - XML

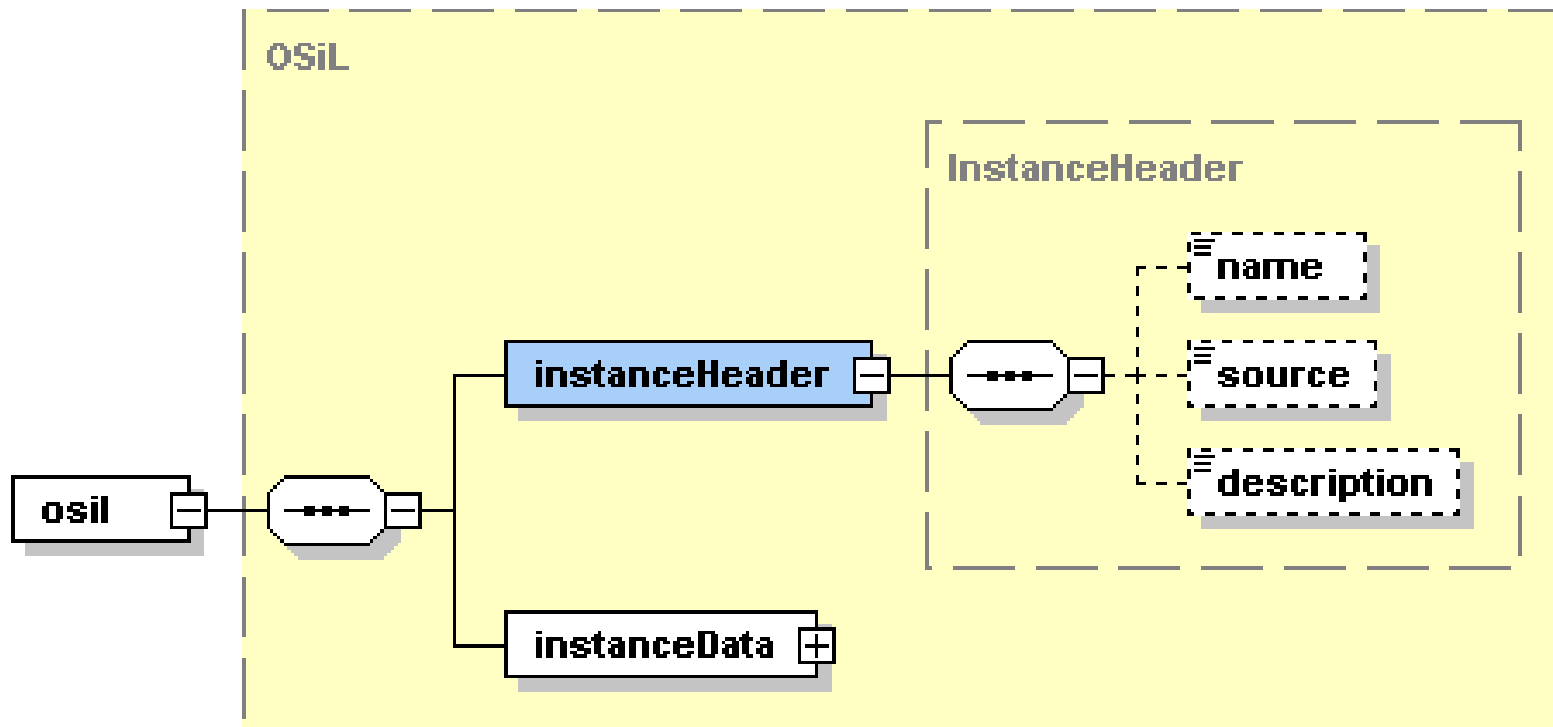


OSiL Schema

- Written in XML
- Very flexible
- Intended to handle as many types of mathematical programs as possible
 - Linear and integer
 - Nonlinear
 - Stochastic
 - ...



OSiL Schema – Header information



Header information – Example

```
<?xmlversion="1.0"encoding="UTF8"?>
<osil xmlns="os.optimizationservices.org"
  xmlns:xsi=http://www.w3.org/2001/XMLSchemainstance
  xsi:schemaLocation="OSiL.xsd">
  <instanceHeader>
    <name>FinancialPlan_JohnBirge</name>
    <source>
      Birge and Louveaux, Stochastic Programming
    </source>
    <description>
      Three-stage stochastic investment problem
    </description>
  </instanceHeader >
  <instanceData>
    ...
  </instanceData>
</osil>
```



OSiL Schema – Deterministic data



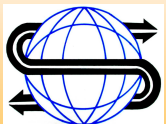
Instance data – Variables, objectives, constraints

```
<variables numberOfVariables="8">
  <var name="invest01" type="C" lb="0.0"/>
  <var name="invest02"/>
  <var name="invest11"/>
  <var name="invest12"/>
  <var name="invest21"/>
  <var name="invest22"/>
  <var name="w"/>
  <var name="u"/>
</variables>
<objectives numberOfObjectives="1">
  <obj maxOrMin="max" numberOfObjCoef="2" lb="0.0">
    <coef idx="6"/>1.</coef>
    <coef idx="7"/>-4.</coef>
  </obj>
</objectives>
<constraints numberOfConstraints="4">
  <con name="budget0" lb="55" ub="55"/>
  <con name="budget1" lb="0" ub="0"/>
  <con name="budget2" lb="0" ub="0"/>
  <con name="budget3" lb="80" ub="80"/>
</constraints>
```

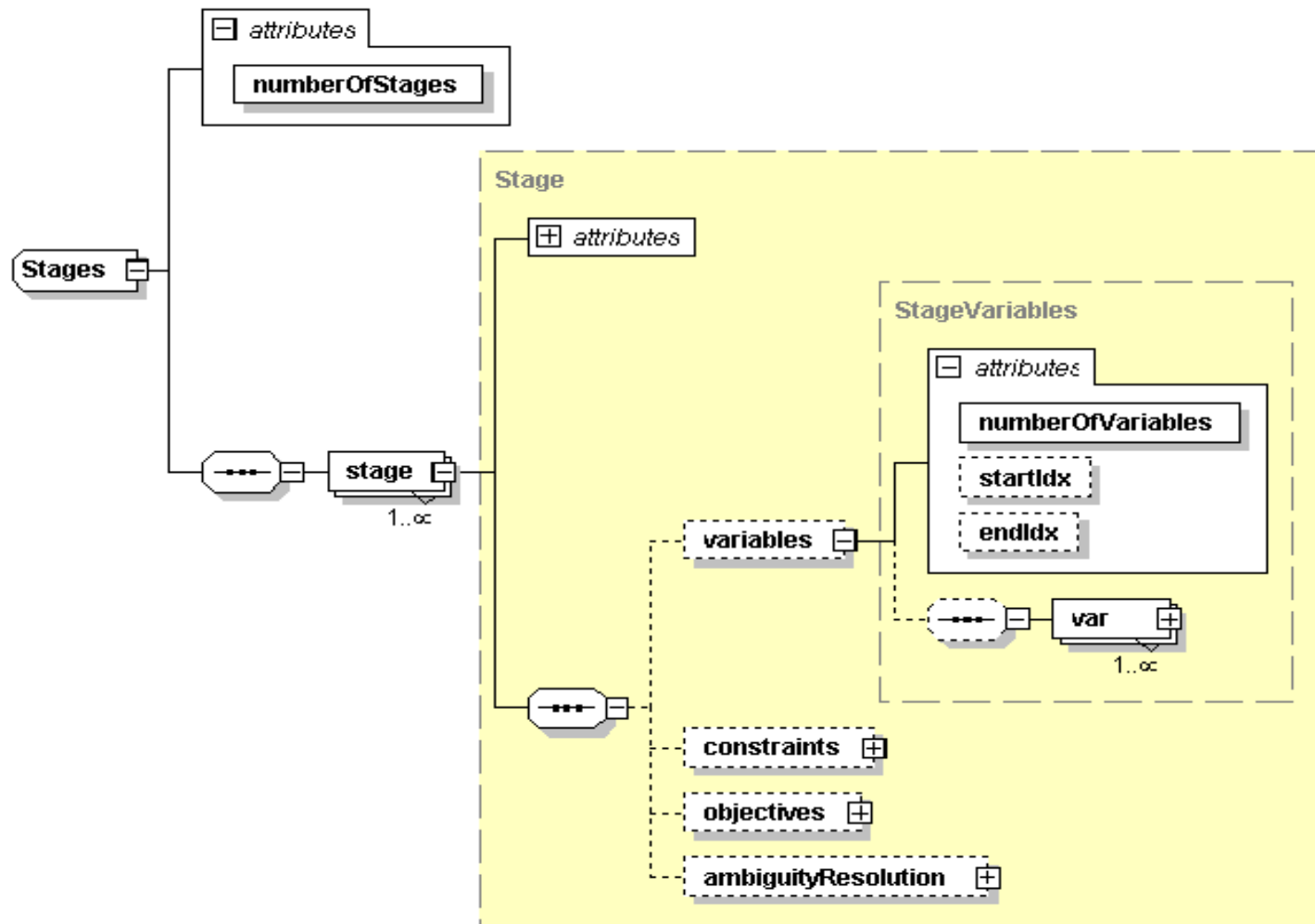


Instance data – Core matrix (sparse matrix form)

<pre> <linearConstraintCoefficients numberOfValues="14"> <start> <el>0</el> <el>2</el> <el>4</el> <el>6</el> <el>8</el> <el>10</el> <el>12</el> <el>13</el> <el>14</el> </start> </pre>	<pre> <rowIdx> <el>0</el> <el>1</el> <el>0</el> <el>1</el> <el>1</el> <el>2</el> <el>1</el> <el>2</el> <el>2</el> <el>2</el> <el>3</el> <el>2</el> <el>3</el> <el>3</el> <el>3</el> </rowIdx> </pre>	<pre> <value> <el>1</el> <el>1.25</el> <el>1</el> <el>1.14</el> <el>1</el> <el>1.25</el> <el>1</el> <el>1.14</el> <el>1</el> <el>1.25</el> <el>1</el> <el>1.14</el> <el>1</el> <el>-1</el> </value> </pre>
---	--	--



OSiL Schema – Dynamic structure

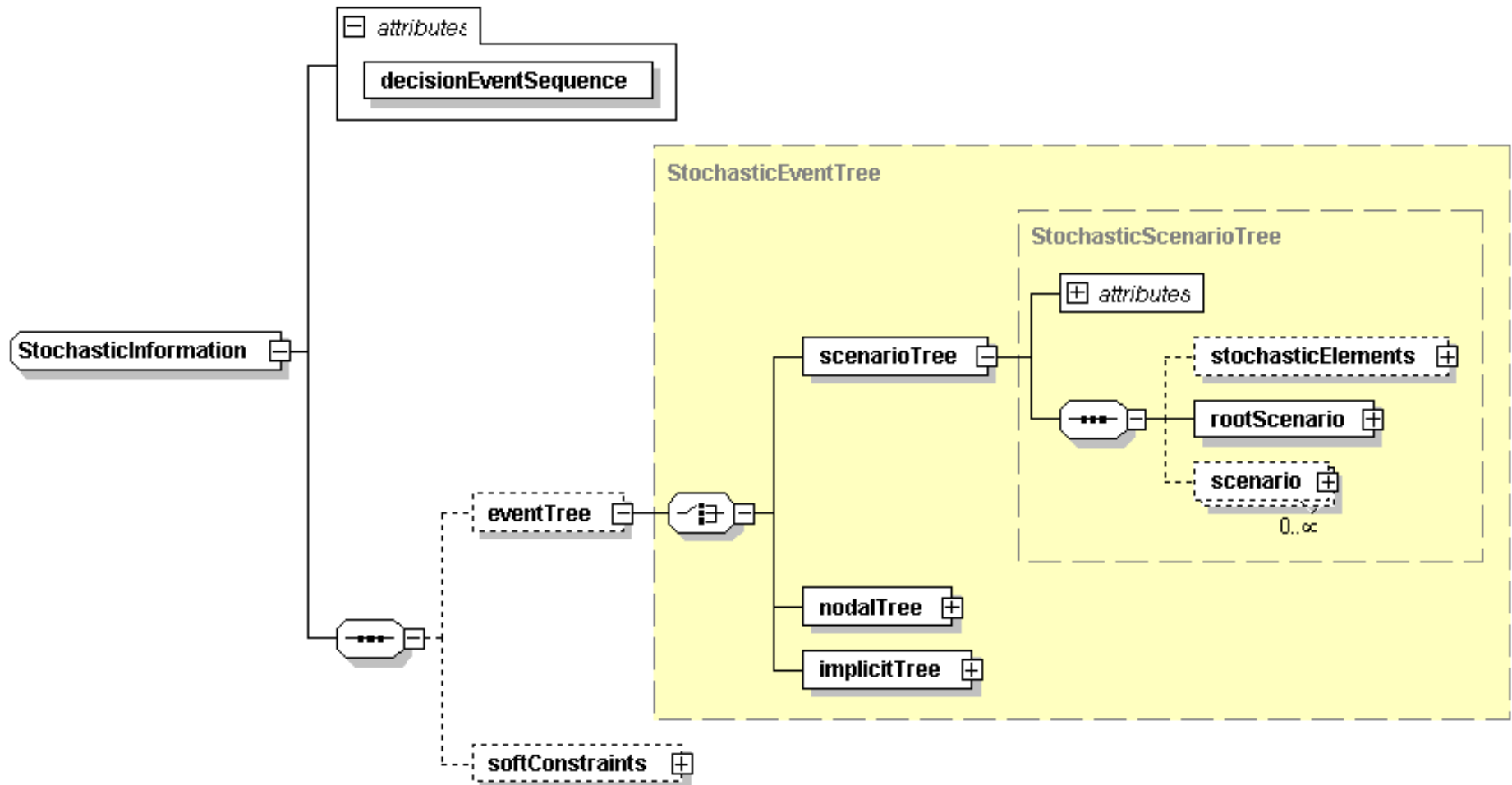


Dynamic information – Example

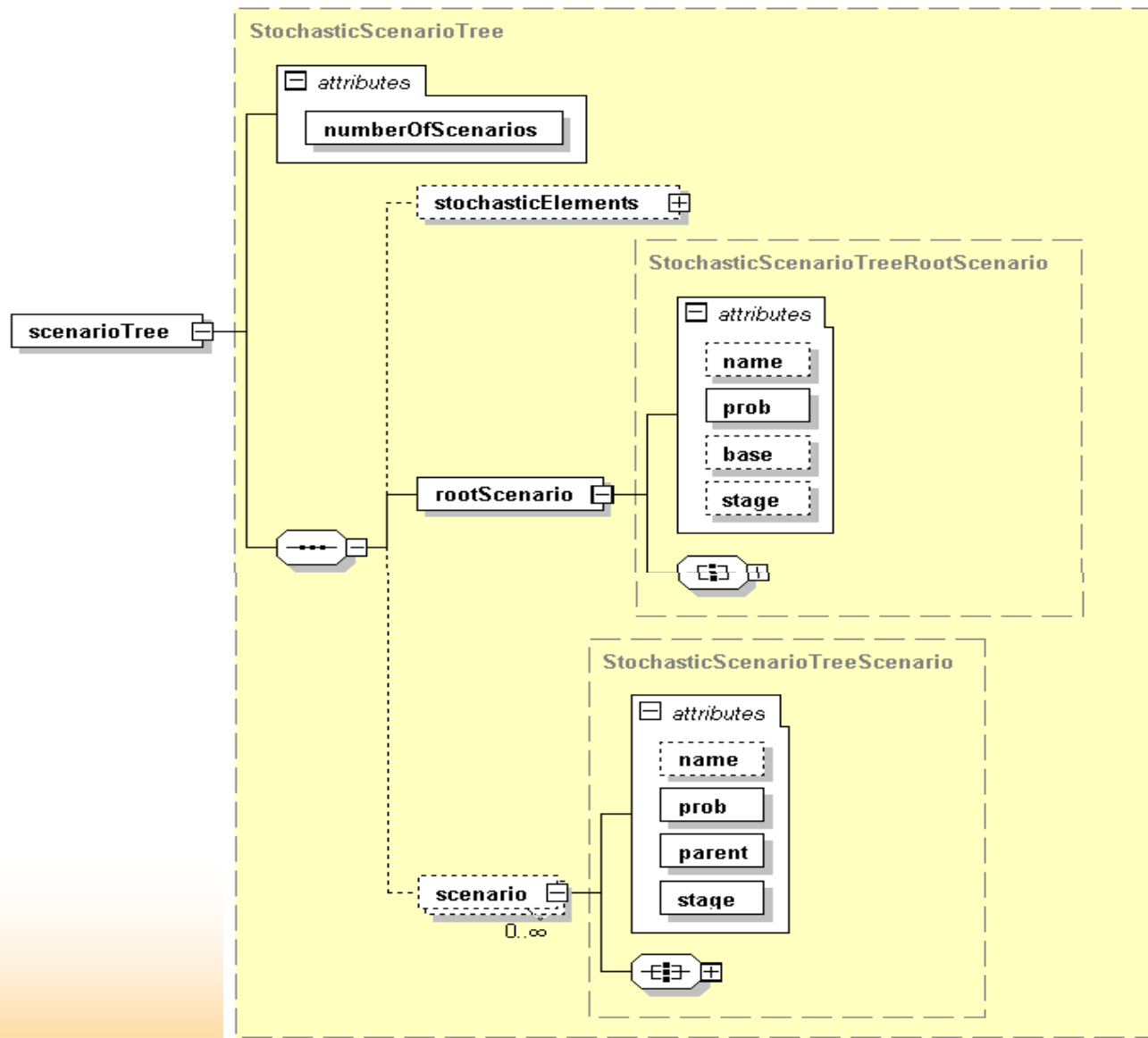
```
<stages numberOfStages="4">
  <stage>
    <variables numberOfVariables="2" startIdx="0" endIdx="1"/>
    <constraints numberOfConstraints="1" startIdx="0"/>
  </stage>
  <stage>
    <variables numberOfVariables="2" startIdx="2" endIdx="3"/>
    <constraints numberOfConstraints="1" startIdx="1"/>
  </stage>
  <stage>
    <variables numberOfVariables="2" startIdx="4" endIdx="5"/>
    <constraints numberOfConstraints="1" startIdx="2"/>
  </stage>
  <stage>
    <variables numberOfVariables="2">
      <var idx="6">      <var idx="7">
    </variables>
    <constraints numberOfConstraints="1" startIdx="3"/>
  </stage>
</stages>
```



Explicit and implicit event trees



OSiL Schema – Scenario trees

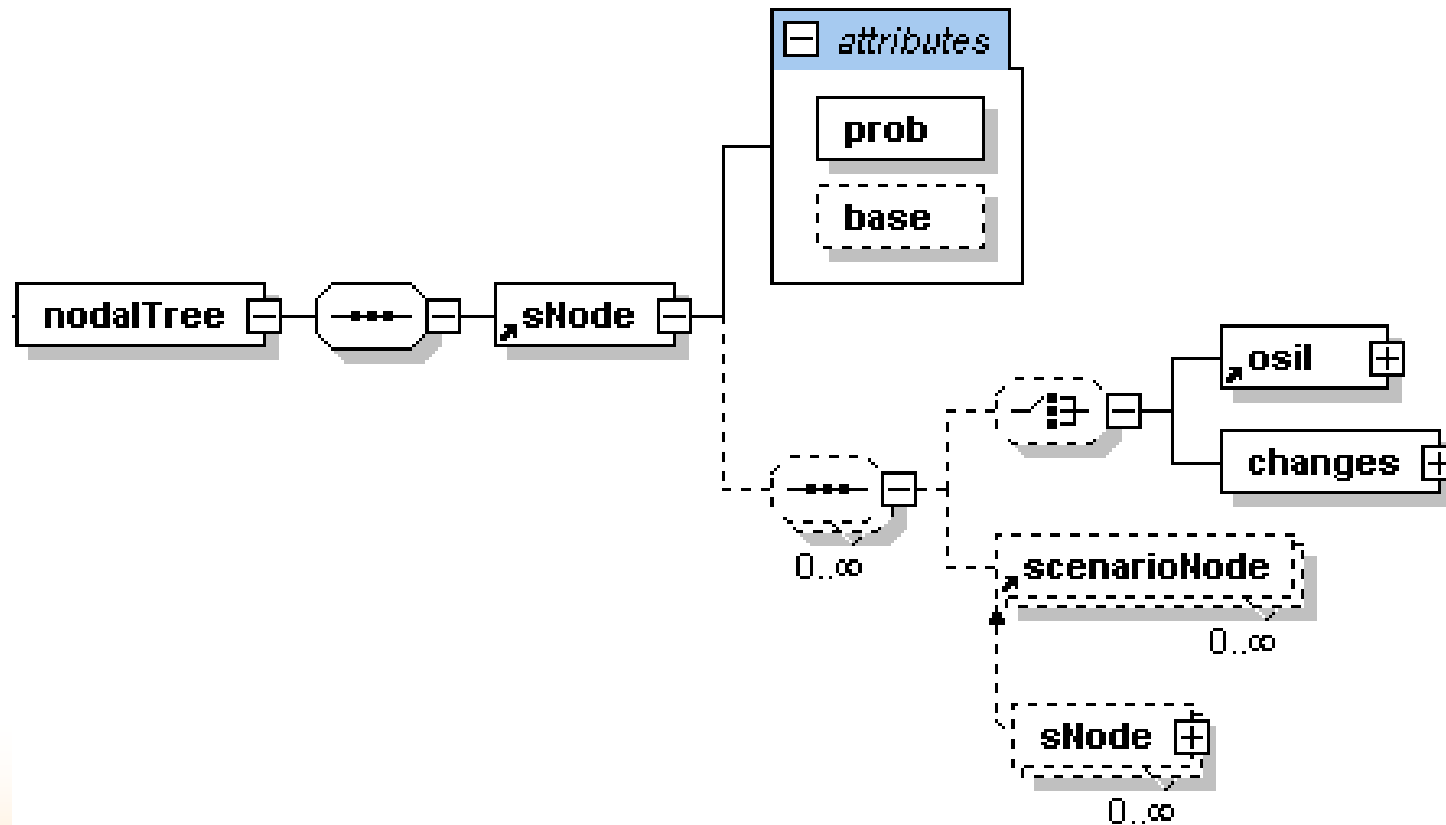


Scenario tree – Example

```
<stochasticInformation
  decisionEvenSequence="DecisionAfterEvent">
  <eventTree>
    <scenarioTree numberOfScenarios="8">
      <rootScenario prob="0.125" stage="0"/>
      <scenario prob="0.125" stage="3" parent="0">
        <linearConstraintCoefficients>
          <el rowIdx="3" colIdx="4">1.06</el>
          <el rowIdx="3" colIdx="5">1.12</el>
        </linearConstraintCoefficients>
      </scenario>
      <scenario prob="0.125" stage="2" parent="0">
        ...
      </scenario>
    </scenarioTree>
  </eventTree>
</stochasticInformation>
```



Node-by-node representation for stochastic problem dimensions



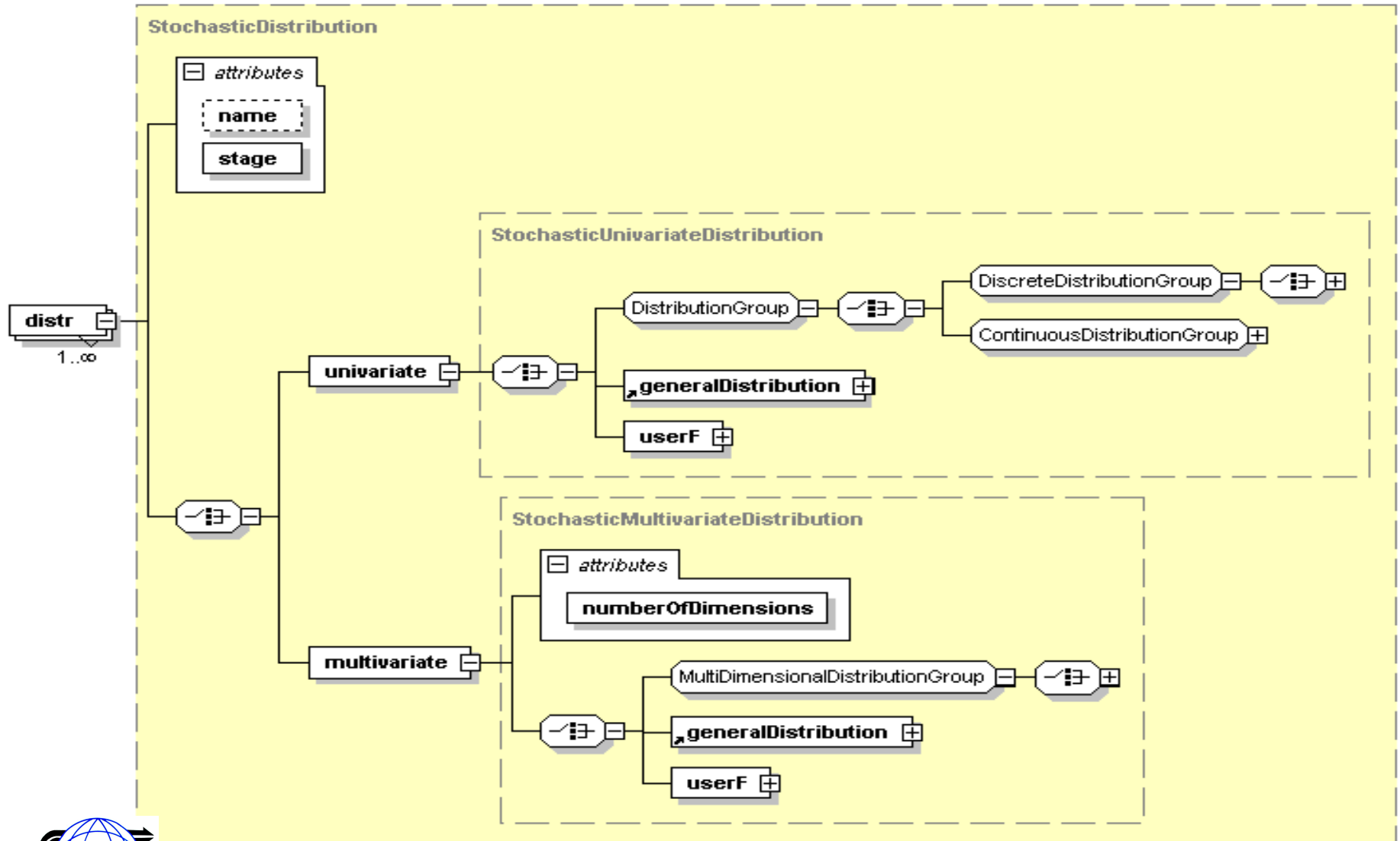
Node-by-node – Example

```
<stochasticInformation
  decisionEvenSequence="DecisionAfterEvent">
  <eventTree >
    <nodalTree>
      <sNode prob="1" base="coreProgram">
        <sNode prob="0.5" base="coreProgram">
          <sNode prob="0.5" base="coreProgram">
            <sNode prob="0.5" base="coreProgram"/>
            <sNode prob="0.5" base="firstSibling">
              <changes>
                <el rowIdx="3" colIdx="4">1.06</el>
                <el rowIdx="3" colIdx="5">1.12</el>
              </changes>
            </sNode>
          </sNode>
        </sNode>
      </sNode>
    </nodalTree>
  </eventTree >
</stochasticInformation
```

...



Distributions (implicit tree)

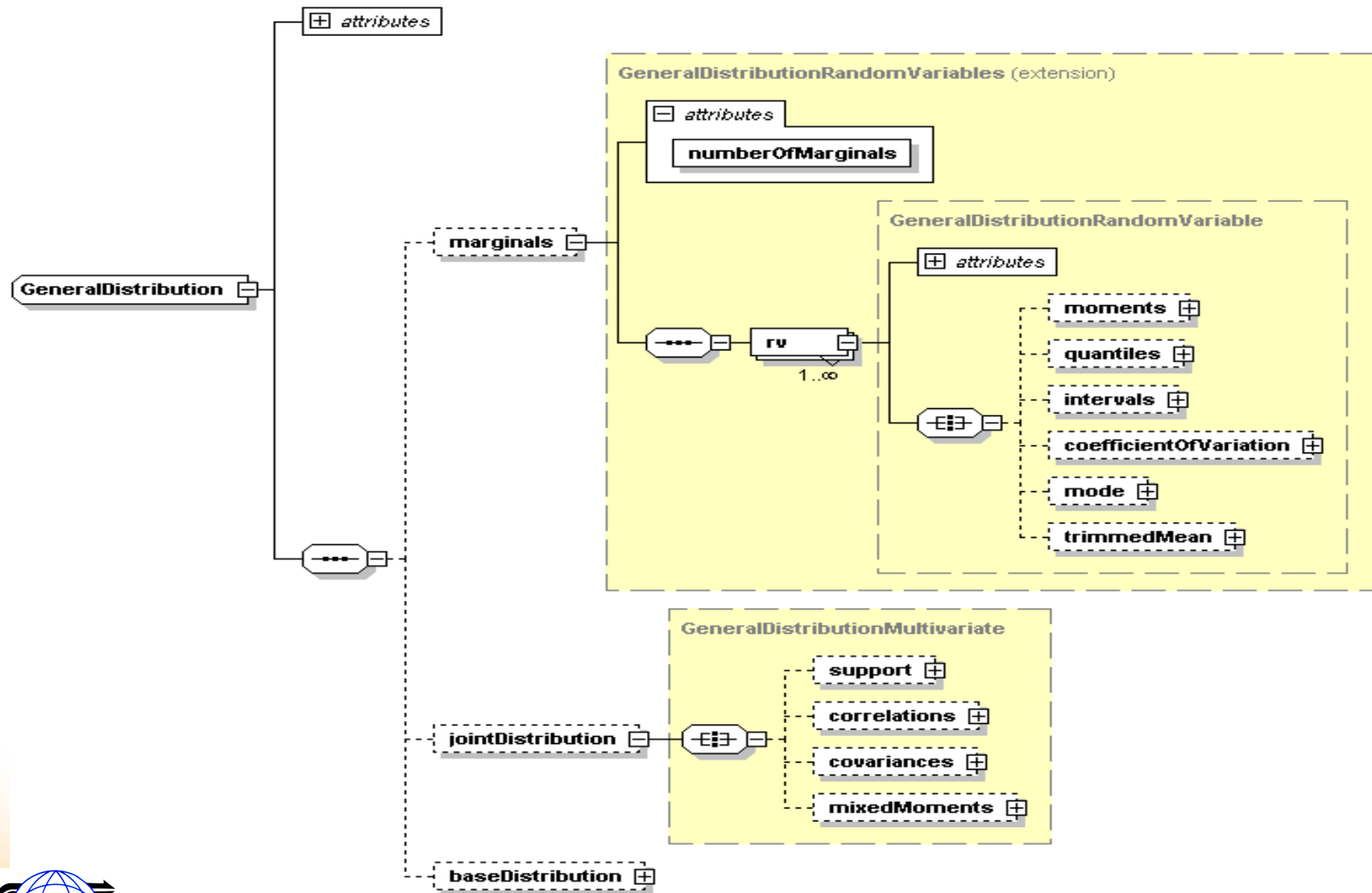


Discrete random vector

```
<distributions>  
  <multivariate>  
    <distr stage="1">  
      <multiDimensionalDistributionGroup>  
        <multivariateDiscrete>  
          <scenario>  
            <prob>0.5</prob>  
            <el>1.25</el>  
            <el>1.14</el>  
          </scenario>  
          <scenario>  
            <prob>0.5</prob>  
            <el>1.06</el>  
            <el>1.12</el>  
          </scenario>  
        </multivariateDiscrete>  
      </multiDimensionalDistributionGroup>  
    </distr>  
    ...  
  </multivariate>  
</distributions>
```

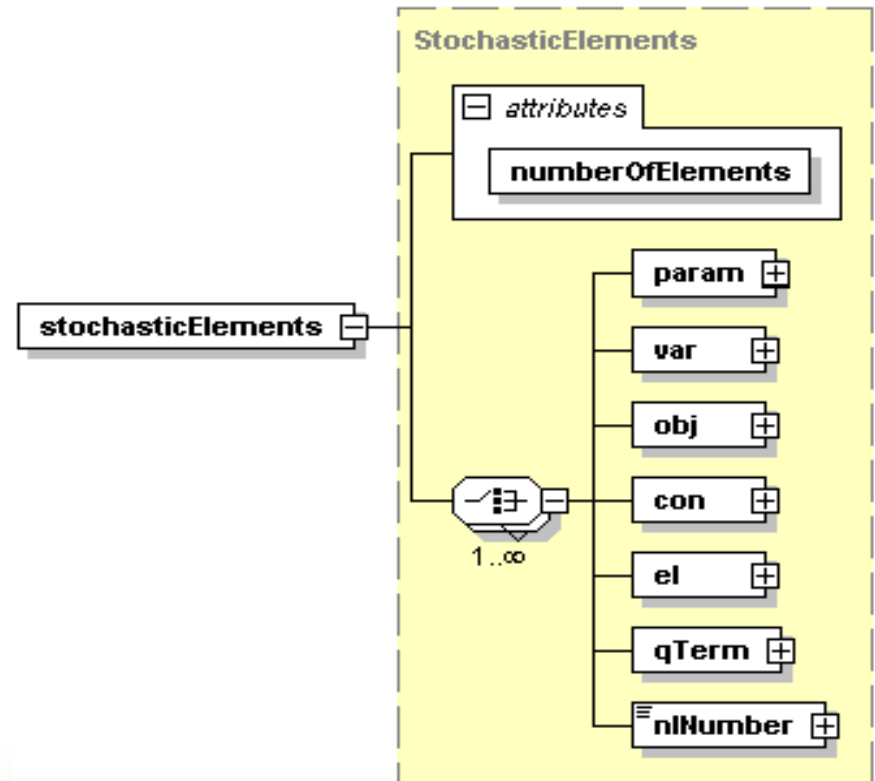


General distribution (incomplete information)

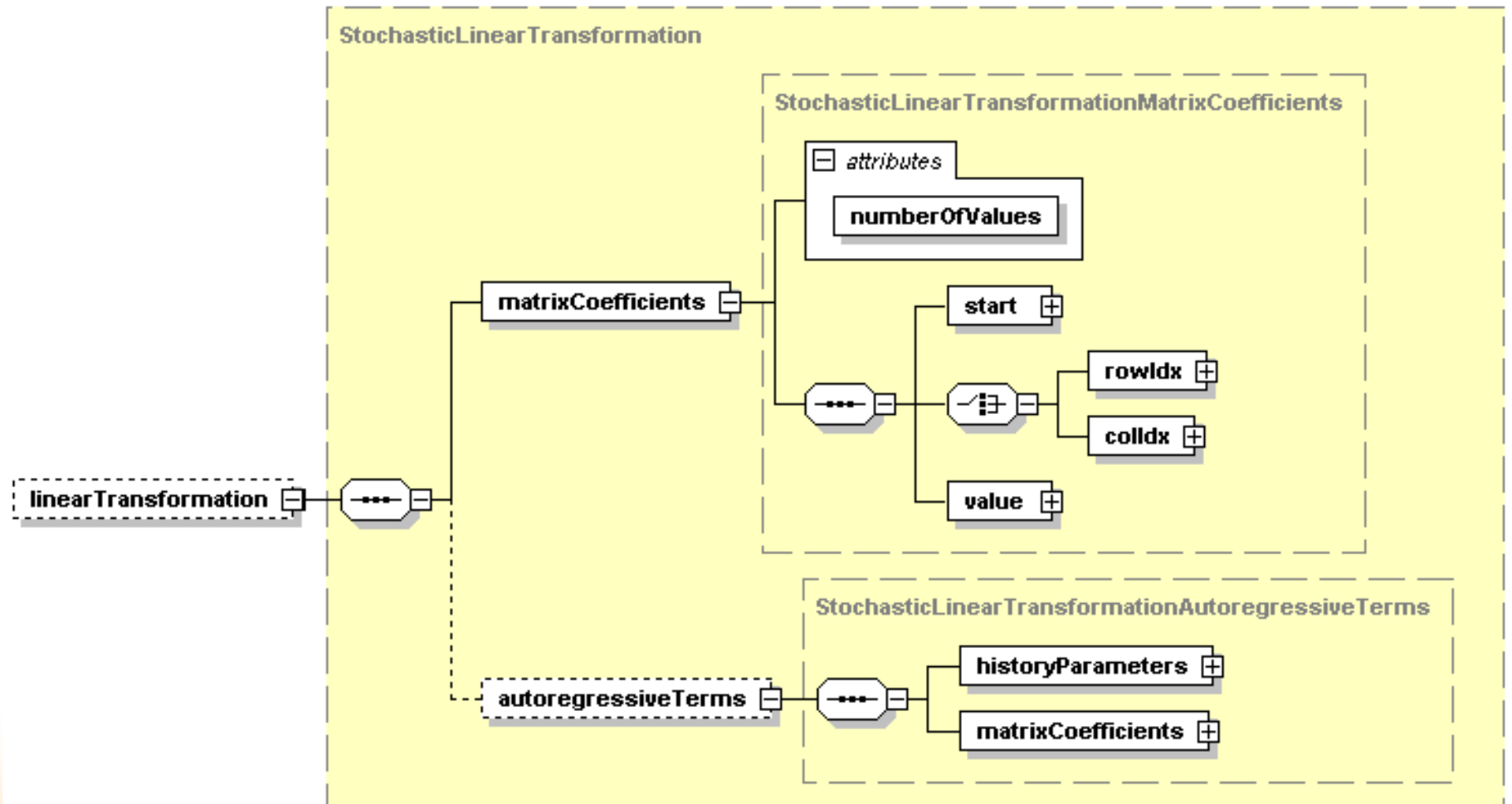


Transformations

- Random variables separated from model entities
- Linked to stochastic problem elements by transformations (linear or nonlinear)
- Useful for factor models and other stochastic processes



OSiL schema – Linear transformations



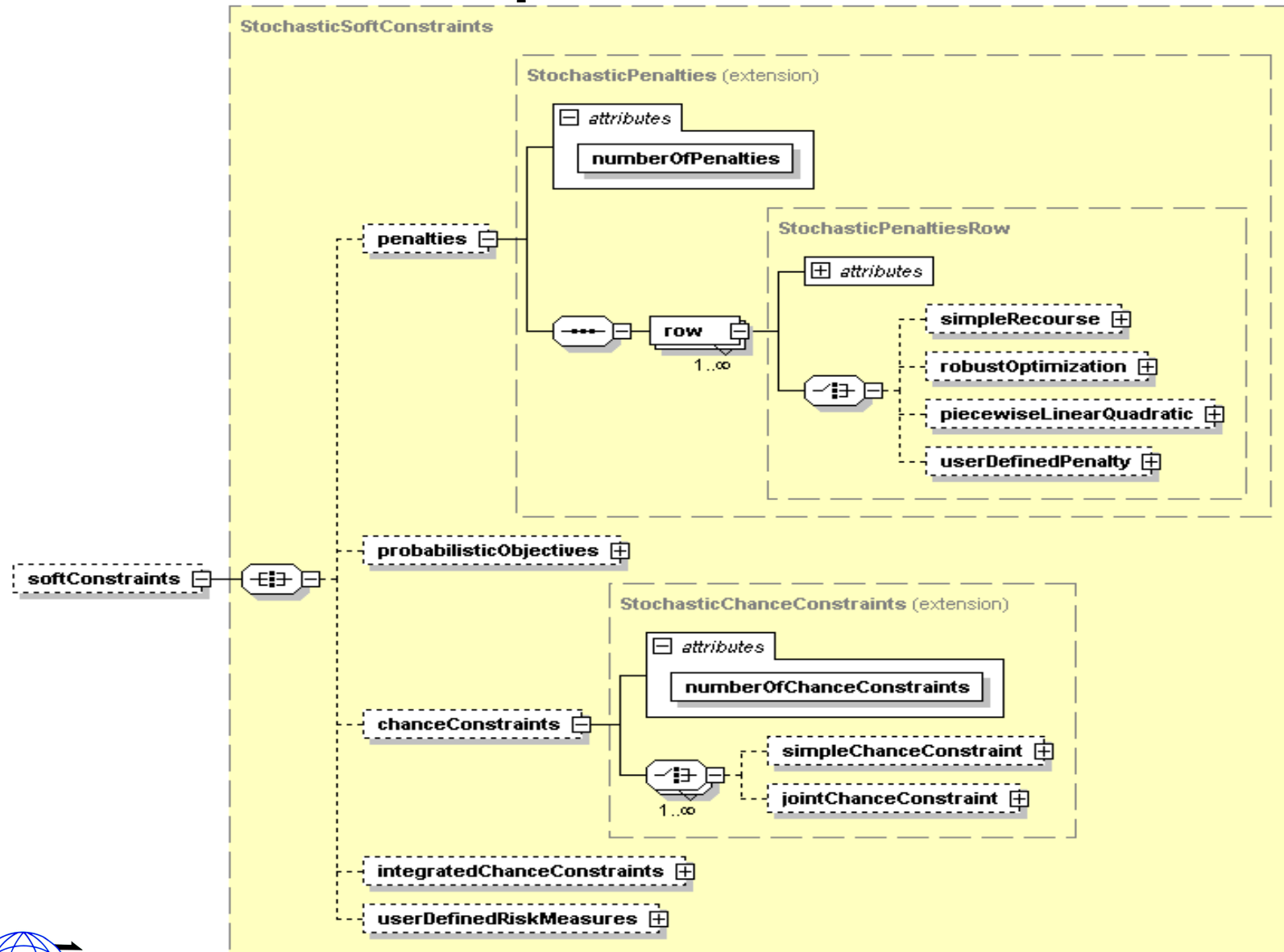
Linear transformation – Example

```
<stochasticTransformation>
  <linearTransformation>
    <stochasticElements
      numberOfElements="6">
        <el rowIdx="1" colIdx="0"/>
        <el rowIdx="1" colIdx="1"/>
        <el rowIdx="2" colIdx="2"/>
        <el rowIdx="2" colIdx="3"/>
        <el rowIdx="3" colIdx="4"/>
        <el rowIdx="3" colIdx="5"/>
      </stochasticElements>
    <matrixCoefficients
      numberOfElements="6">
    <start>
      <el>0</el>
      <el>1</el>
      <el>2</el>
      <el>3</el>
      <el>4</el>
      <el>5</el>
      <el>6</el>
    </start>
```

```
<rowIdx>
  <el>0</el>
  <el>1</el>
  <el>2</el>
  <el>3</el>
  <el>4</el>
  <el>1</el>
</rowIdx>
<value>
  <el mult="6">1.0</el>
</value>
</matrixCoefficients>
</linearTransformation>
</stochasticTransformation>
```



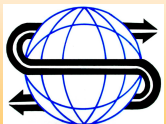
Penalties and probabilistic constraints



Nonlinear expression –

$$(2x_0 - x_1^2)^2 + (1 - x_0)^2$$

```
<plus>
  <power>
    <minus>
      <var coef="2.0" idx="0"/>
      <power>
        <var coef="1.0" idx="1"/>
        <number value="2"/>
      </power>
    </minus>
    <number value="2"/>
  </power>
  <power>
    <minus>
      <number value="1"/>
      <var coef="1.0" idx="0"/>
    </minus>
    <number value="2"/>
  </power>
</plus>
```



Capabilities

- Arbitrary nonlinear expressions
- Arbitrary distributions
- Scenario trees
- Stochastic problem dimensions
- Simple recourse
- Soft constraints with arbitrary penalties
- Probabilistic constraints
- Arbitrary moment constraints

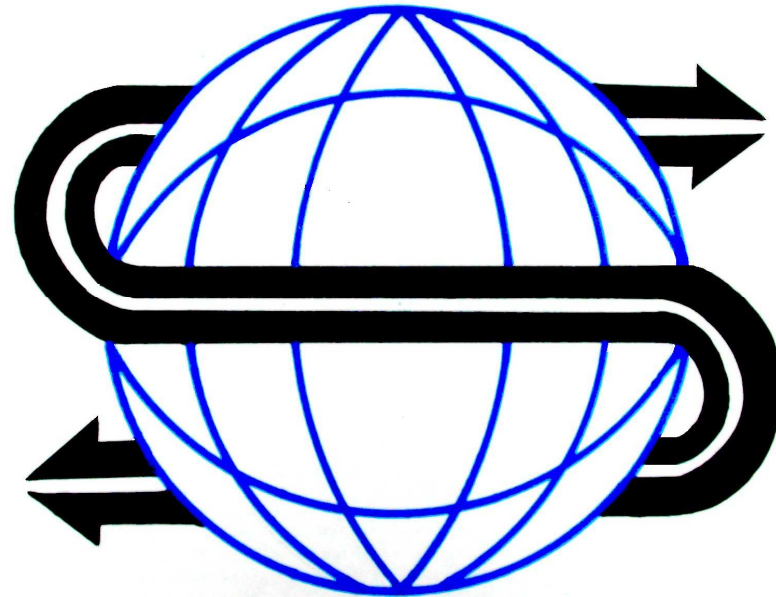


Further work

- Internal data structures (OSInstance)
- OSiLWriter: SMPS → OSiL
- Library of problems (netlib, POSTS, Ariyawansa and Felt, Watson, SIPLib,...)
- Readers
- Solver interfaces
- Buy-in



QUESTIONS?



<http://www.optimizationservices.org>

<http://myweb.dal.ca/gassmann>



© 2007 H.I. Gassmann